Embedded Android

Delivered and/or customized by

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About

- Author of:
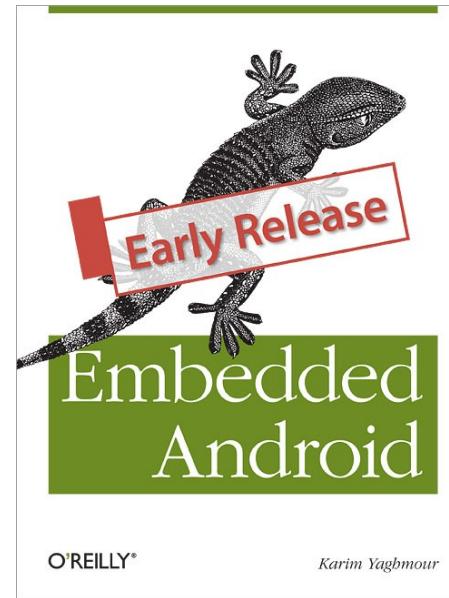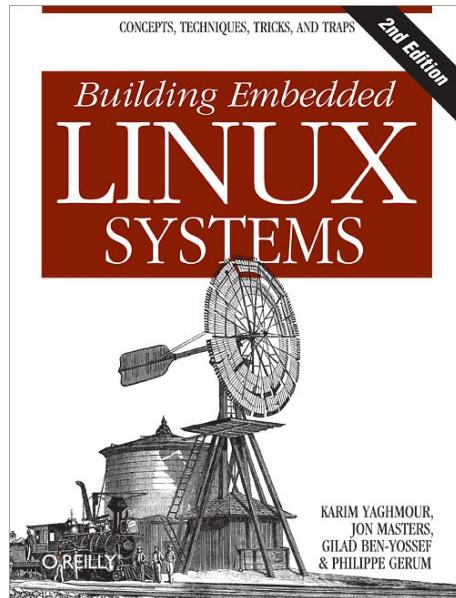
- Introduced Linux Trace Toolkit in 1999

- Originated Adeos and relayfs (kernel/relay.c)

- Training, Custom Dev, Consulting, ...

About Android

- Huge

- Fast moving

- Stealthy

Goals

- Master the intricacies of all components making up Android, including kernel Androidisms

- Get hands-on experience in building and customizing Android-based embedded systems

- Learn basics of Android app development

- Familiarize with the Android ecosystem

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Format

- Tracks:
    - Lecture
    - Exercises
- Fast pace
- Lots of material

Requirements

- Embedded systems development

- C, C++

- Basic Unix/Linux command line interface experience

- Java (working knowledge of) and/or fast learner ;)

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Knowledge Fields

- Main fields:

  - Embedded systems

  - Linux kernel internals

  - Device driver development

  - Unix system administration

  - GNU software development

  - Java-based development

  - Android app development

- Vastly different fields, few (if any) master all

- Fluency required to tackle tough problems

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Topics

- Setting context:
    - Introduction to embedded Android
    - Concepts and internals
    - Android Open Source Project (AOSP)
    - Kernel basics
- Android Essentials:
    - Embedded Linux root FS
    - Native Android user-space
    - System Server
    - Hardware Abstraction Layer
    - Android Framework

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- Custom toolchains and dev kits
- Compatibility Test Suite
- Hacks, Variants, Tricks and Resources
- Hardware porting and support:
  - Manipulating solid-state storage devices
  - Choosing and installing the root filesystem
  - Kernel internals
  - Device driver development overview
- Additional material:
  - A quick Java introduction

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- Niche topics:

  - 3rd party projects, resources and tools

  - Compatibility Test Suite

Courseware

- These slides

- Exercises

- Android documentation:

  - source.android.com

  - developer.android.com

  - tools.android.com

- Android Open Source Project:

  'Use the Source, Luke, use the Source. Be one with the code.' -- Linus Torvalds

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Hands-On Environment

- Host:
  - Ubuntu 64-bit 10.04 or 10.10
  - 10GB / AOSP (source is 4GB / AOSP)
- QEMU:
  - Same emulator used for App development
  - Originally at: www.qemu.org
  - Shipped with AOSP
  - Expandable (can create new "hardware" via .so files)
  - Has been around for a long time

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Introduction to Embedded Android

- Basics

- History

- Ecosystem

- Legal framework

- Platform and hardware requirements

- Development tools

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1. Basics

- Features
- UX Concepts
- App Concepts

1.1. Features

- Application framework enabling reuse and replacement of components

- Dalvik virtual machine optimized for mobile devices

- Integrated browser based on the open source WebKit engine

- Optimized graphics powered by a custom 2D graphics library; 3D graphics based on the OpenGL ES 1.0 specification (hardware acceleration optional)

- SQLite for structured data storage

- Media support for common audio, video, and still image formats (MPEG4, H.264, MP3, AAC, AMR, JPG, PNG, GIF)

- GSM Telephony (hardware dependent)

- Bluetooth, EDGE, 3G, and WiFi (hardware dependent)

- Camera, GPS, compass, and accelerometer (hardware dependent)

- Rich development environment including a device emulator, tools for debugging, memory and performance profiling, and a plugin for the Eclipse IDE

1.2. UX Concepts

- Browser-like

- iPhone-ish

- No user-concept of "task"

- Main keys:

  - HOME

  - SEARCH

  - BACK

  - MENU

- App-model allows users to safely install/test almost anything

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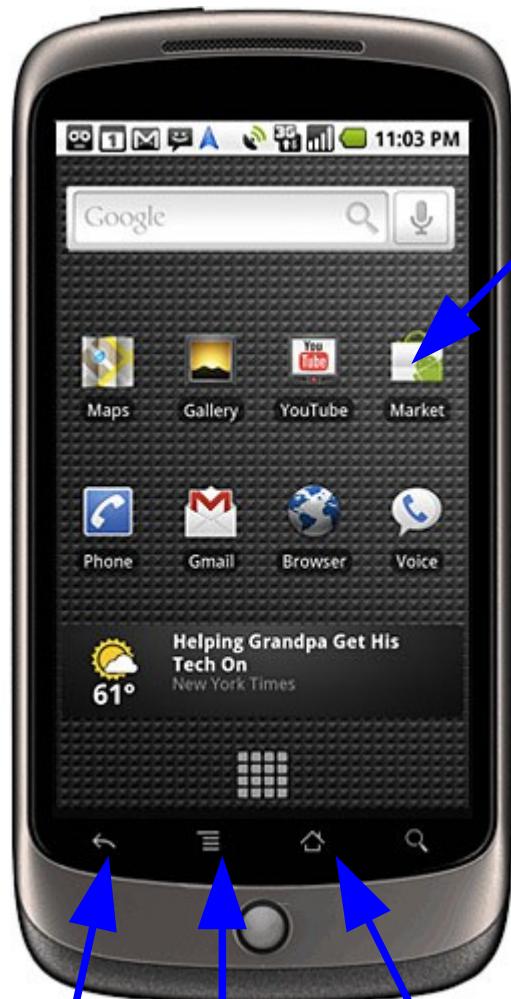
Activity

Back

Menu

Home

"Click" → Activity #1

"Back" "Click"

Activity #2

"Back" "Click"

Activity #3

"Home"

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1.3. App Concepts

- No single entry point (No main() !?!?)

- Unlike Windows or Unix API/semantics in many ways

- Processes and apps will be killed at random: developer must code accordingly

- UI disintermediated from app "brains"

- Apps are isolated, very

- Behavior predicated on low-memory conditions

2. History

- 2002:
  - Sergey Brin and Larry Page started using Sidekick smartphone
  - Sidedick one of 1st smartphones integrating web, IM, mail, etc.
  - Sidedick was made by Danger inc., co-founded by Andy Rubin (CEO)
  - Brin/Page met Rubin at Stanford talk he gave on Sidekick's development
  - Google was default search engine on Sidekick
- 2004:
  - Despite cult following, Sidekick wasn't making $
  - Danger inc. board decided to replace Rubin
  - Rubin left. Got seed $. Started Android inc. Started looking for VCs.
  - Goal: Open mobile hand-set platform
- 2005 - July:
  - Got bought by Google for undisclosed sum :)
- 2007 - November:
  - Open Handset Alliance announced along with Android

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- 2008 - Sept.: Android 1.0 / "Astro"
- 2009 - Feb.: Android 1.1 / "Bender"
- 2009 - Apr.: Android 1.5 / Cupcake
- 2009 - Sept.: Android 1.6 / Donut
- 2009 - Oct.: Android 2.0/2.1 / Eclair
- 2010 - May: Android 2.2 / Froyo
- 2010 - Dec.: Android 2.3 / Gingerbread
- 2011 - Jan : Android 3.0 / Honeycomb – Tablet-optimized
- 2011 – May: Android 3.1 – USB host support
- 2011 – Nov: Android 4.0 / Ice-Cream Sandwich – merge Gingerbread and Honeycomb

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3. Ecosystem

- 850k phone activations per day

- 400k apps (vs. 585k for Apple's app store)

- ~50% total US smartphone subscribers

- ...

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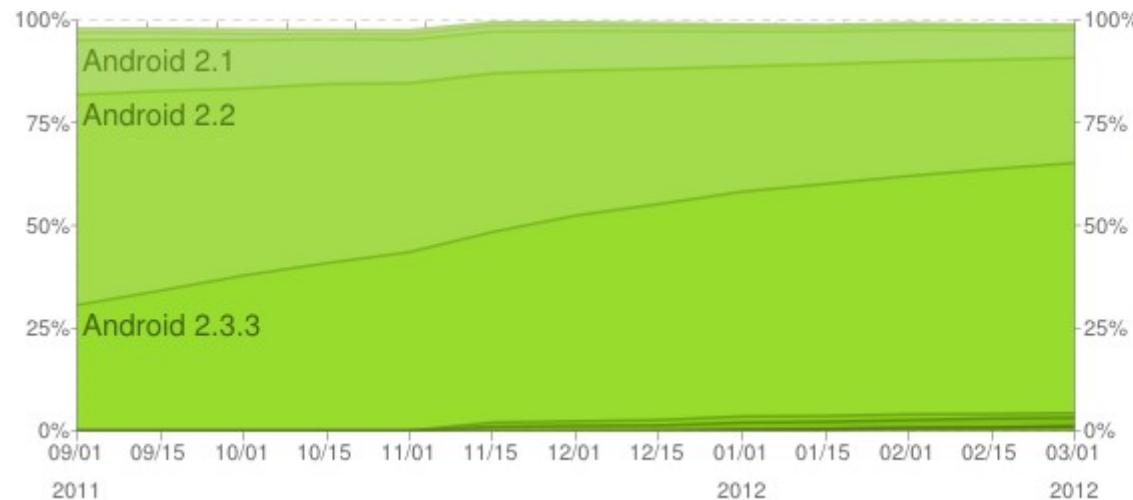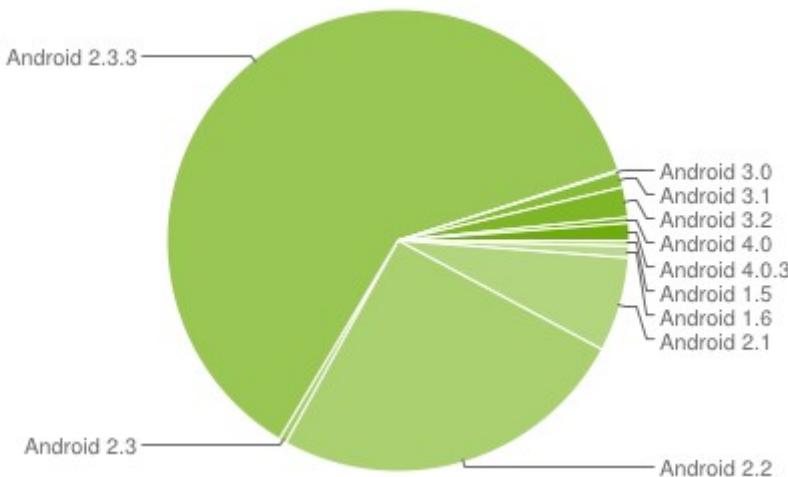
3.1. Who's playing?

- Leading IP:
  - Google
- Semiconductor manufacturers:
  - ARM, Intel, Freescale, TI, Qualcomm, NVIDIA, ...
- Handset manufacturers:
  - Motorola, Samsung, HTC, LG, Sony-Ericsson, ...
- Tablet manufacturers:
  - Motorola, Samsung, Archos, DELL, ASUS, ...
- Special-purpose devices:
  - Nook, Joint Battle Command-Platform, ...
- App stores:
  - Android Market, Amazon App Store, V CAST Apps, B&N NOOK Apps, ...

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3.2. Open Handset Alliance

- "... a group of 80 technology and mobile companies who have come together to accelerate innovation in mobile and offer consumers a richer, less expensive, and better mobile experience. Together we have developed Android™, the first complete, open, and free mobile platform."

- Unclear what OHA does or what benefits, if any, members derive

- <u>Not</u> an organization with board members, staff, etc. ... just an "Alliance"

- Google's Android team are the lead on all bleeding edge dev, all else tag along

- OHA is largely inactive / absent

- Comprised of:
    - Mobile Operators: Sprint, T-Mobile, Vodafone, NTT Docomo, ...
    - Handset Manufacturers: HTC, Motorola, LG, Samsung, Sony Ericsson, ...
    - Semiconductor Companies: ARM, Freescale, Intel, NVIDIA, Qualcomm, TI, ...
    - Software Companies: Google, ...
    - Commercialization Companies: ...

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4. Legal Framework

- Code access

- Code licenses

- Branding use

- Google's own Android Apps

- Alternative App stores

- Oracle v. Google

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4.1. Code Access

- Parts:
  - Kernel
  - Android Open Source Project (AOSP)
- Kernel:
  - Should have access to latest shipped version => GPL requirement
  - Google-maintained forks at android.googlesource.com
- AOSP:
  - *Usually* Code-drops every 6 months
  - Official AOSP branches at android.googlesource.com
  - Managed by "repo" tool, an overlay to "git"
- Honeycomb (3.0) code requires talking to Google
  - ... which hasn't precluded moders from lifting binaries off the SDK and putting Honeycomb on all sorts of devices, including B&N's Nook ...

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4.2. Code Licenses

- Kernel:
  - GNU General Public License (a.k.a. GPL)
- AOSP:
  - Mostly Apache License 2.0 (a.k.a. ASL)
  - Having GPL-free user-space was a design goal
  - A few GPL and LGPL parts: mainly BlueZ and DBUS
  - Some key components in BSD: Bionic and Toolbox
  - "external/" directory contains a mixed bag of licenses, incl. lots of GPL
- May be desirable to add GPL/LGPL components:
  - BusyBox
  - uClibc / eglibc / glibc

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4.3. Branding Use

- Android Robot:
  - Very much like the Linux penguin
- Android Logo (A-N-D-R-O-I-D w/ typeface):
  - Cannot be used
- Android Custom Typeface:
  - Cannot be used
- Android in Official Names:
  - As descriptor only: "for Android"
  - Most other uses require approval
- Android in Messaging:
  - Allowed if followed by a generic: "Android Application"
- Compliance through CDD/CTS involved in "approval"

4.4. Google's own Android Apps

- The non-AOSP apps:
  - Android Market
  - YouTube
  - Maps and Navigation
  - Gmail
  - Voice
  - SkyMap
  - ...
- Require:
  - CTS/CDD Compliance
  - Signed agreement w/ Google
- Inquiries: android-partnerships@google.com

4.5. Alternative "App Stores"

- A couple of stores are already public:
  - Android Market
  - Amazon App Store
  - V CAST Apps
  - B&N NOOK Apps
  - ...
- Nothing precluding you from having your own

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4.6. Oracle v. Google

- Filed August 2010

- Patent infringement:

  - 6,125,447; 6,192,476; 5,966,702; 7,426,720; RE38,104; 6,910,205; and 6,061,520

- Copyright infringement:

- Android does not use any Oracle Java libraries or JVM in the final product.

- Android relies on Apache Harmony and Dalvik instead.

- In October 2010, IBM left Apache Harmony to join work on Oracle's OpenJDK, leaving the project practically orphaned.

- In May 2011, judge orders claims cut from 132 to 3 and prior art references cut from hundreds to 8

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5. Platform and Hardware requirements

- In principle:
  - Android runs on top of Linux
  - Therefore: if it runs Linux, it can run Android
- Known to have been made to work on:
  - ARM
  - x86
  - MIPS
  - SuperH
- Put in all sort of devices:
  - Washers, micro-wave ovens, car systems, etc.

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5.1. Compliance Definition Document

- Software: MUST conform to AOSP

- Application Packaging Compatibility: support ".apk" files

- Multimedia Compatibility: decoders, encoders, recording, ...

- Developer Tool Compatibility: adb, ddms, Monkey

- Hardware compatibility:

  - Display and Graphics

  - Input Devices

  - Data Connectivity

  - Cameras

  - Memory and Storage

  - USB

- Performance Compatibility

- Security Model Compatibility

- Software Compatibility Testing

- Updatable Software: MUST include mechanism to update

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5.2. Compatibility Test Suite

On your machine

Download and install the CTS.

Run the CTS.

Store and view results.

Devices you attach to your machine

Test execution

Test results

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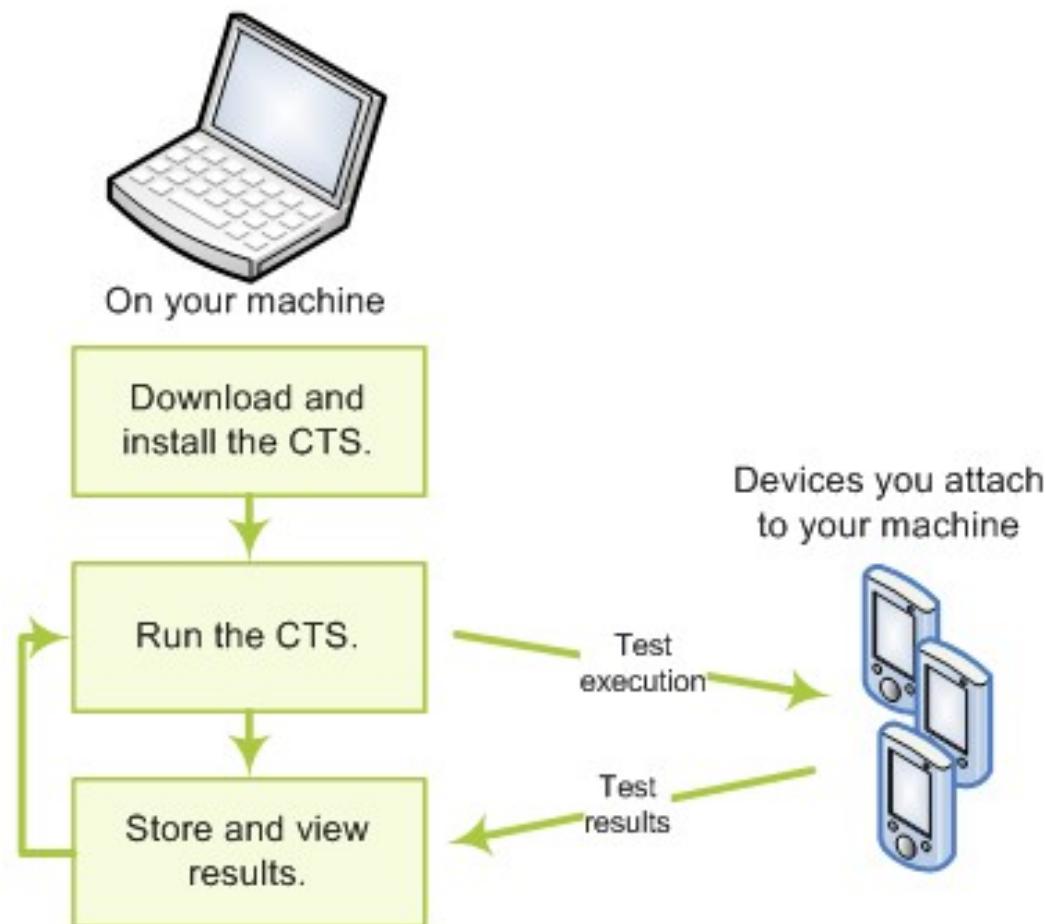
6. Development tools

- Requirements

- App dev tools and resources

- App debugging

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6.1. Requirements

- App development and debugging:
  - Windows / Mac / Linux workstation
  - JDK
  - Eclipse w/ ADT plugin
  - Highly recommended: real device(**S**)
- Platform development:
  - GNU cross-dev toolchain
  - JTAG debugger
  - ... more on this later

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6.2. App dev tools and resources

- SDK:
  - android – manage AVDs and SDK components
  - apkbuilder – creating .apk packages
  - dx – converting .jar to .dex
  - adb – debug bridge
  - ...
- Emulator – QEMU-based ARM emulator
  - Use KVM for x86 instead
- NDK: GNU toolchain for native binaries
- Documentation: developer.android.com

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Android Package (.apk)

.dex files	resources .arsc
uncompiled resources	
AndroidManifest.xml	

Android Project → Compilation and Packaging → Android Package (.apk) → Signing —ADB→ Device or Emulator

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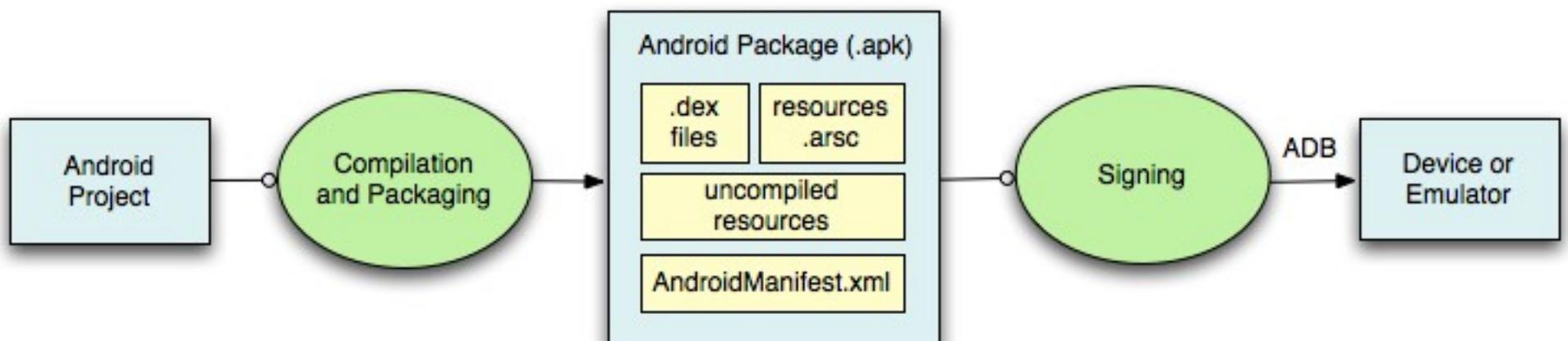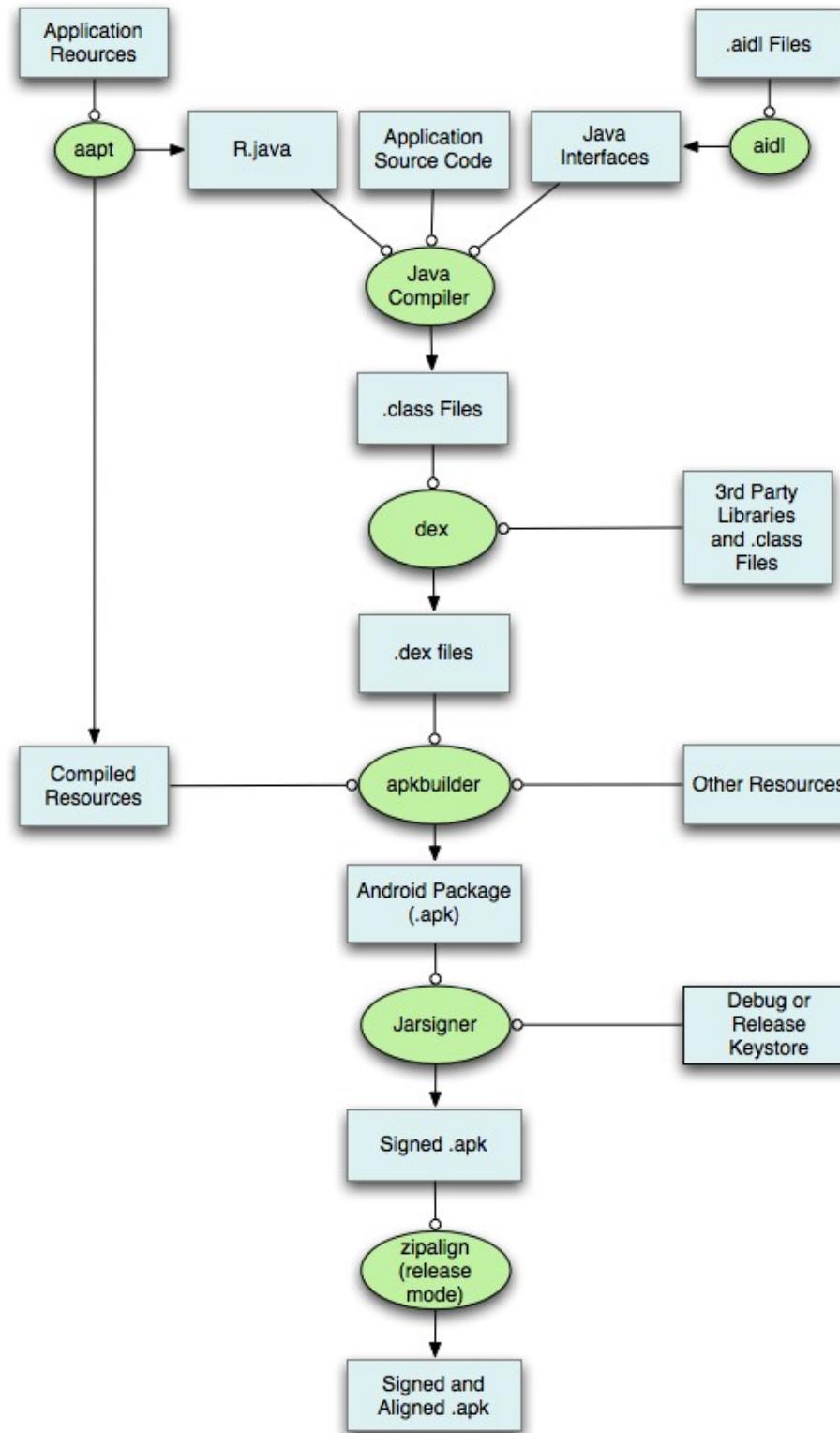
6.3. App debugging

- adb
- ddms
- monkeyrunner
- traceview
- logcat
- Eclipse integration (ADT plugin)

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Concepts and Internals

1. Android Concepts
2. Framework Intro
3. Native Development
4. Overall Architecture
5. System startup
6. Linux Kernel
7. Hardware Support
8. Native User-Space

9. Dalvik
10. JNI
11. System Server
12. Calling on Services
13. Activity Manager
14. Binder
15. Stock AOSP Apps

1. Android Concepts

- Components

- Intents

- Component lifecycle

- Manifest file

- Processes and threads

- Remote procedure calls

1.1. Components

- 1 App = N Components

- Apps can use components of other applications

- App processes are automagically started whenever any part is needed

- Ergo: N entry points, !1, and !main()

- Components:

  - Activities

  - Services

  - Broadcast Receivers

  - Content Providers

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1.2. Intents

- Intent = asynchronous message w/ or w/o designated target

- Like a polymorphic Unix signal, but w/o required target

- Intents "payload" held in Intent Object

- Intent Filters specified in Manifest file

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1.3. Component lifecycle

- System automagically starts/stops/kills processes:

  - Entire system behaviour predicated on low memory

- System triggers Lifecycle callbacks when relevant

- Ergo: Must manage Component Lifecycle

- Some Components are more complex to manage than others

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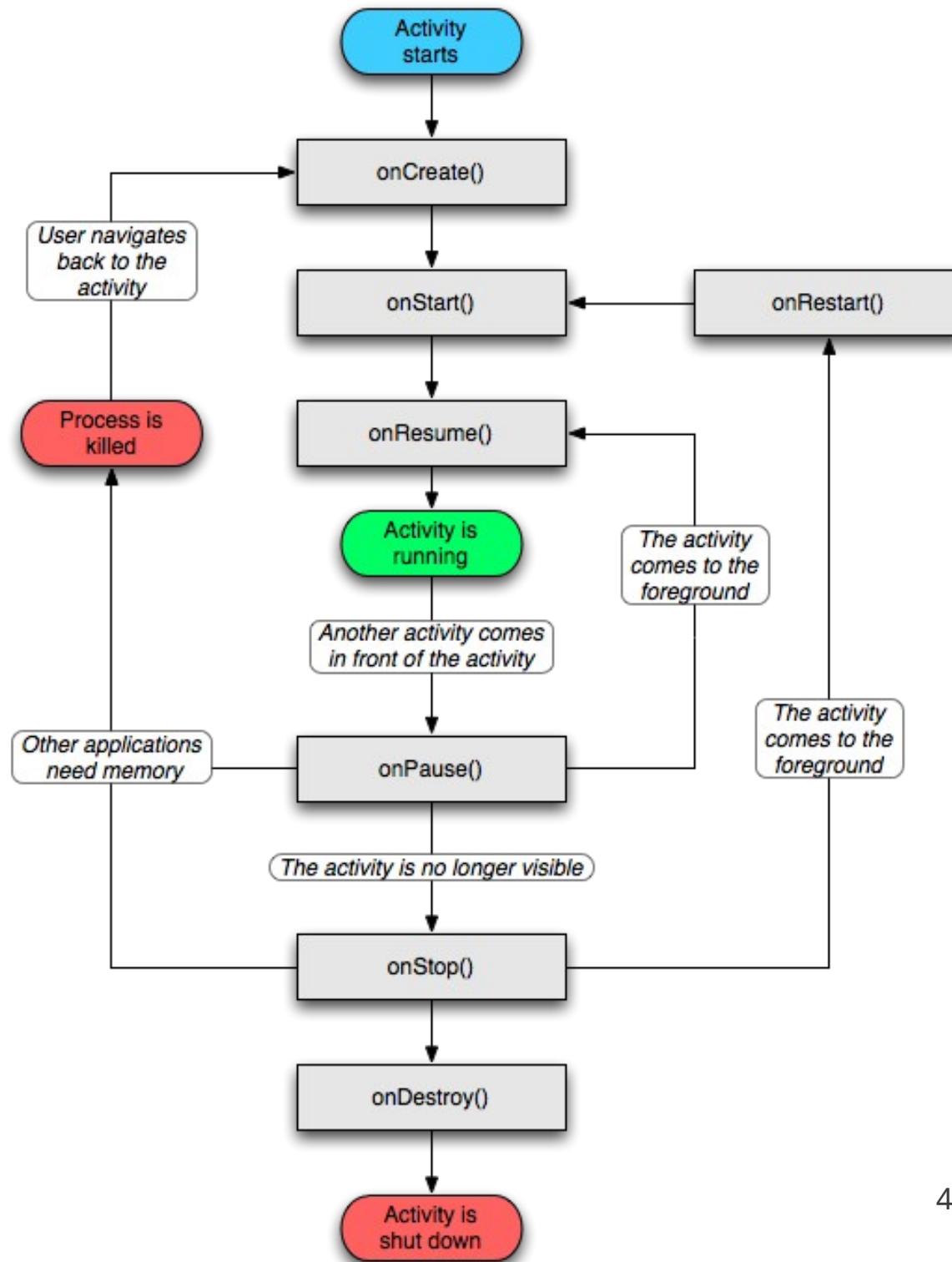
1.4. Manifest file

- Informs system about app's components

- XML format

- Always called AndroidManifest.xml

- Activity = <activity> ... static

- Service = <service> ... static

- Broadcast Receiver:

  - Static = <receiver>

  - Dynamic = Context.registerReceiver()

- Content Provider = <provider> ... static

1.5. Processes and threads

- Processes
  - Default: all callbacks to any app Component are issued to the main process thread
  - \<activity\>—\<service\>—\<recipient\>—\<provider\> have process attribute to override default
  - Do NOT perform blocking/long operations in main process thread:
    – Spawn threads instead
  - Process termination/restart is at system's discretion
  - Therefore:
    – Must manage Component Lifecycle
- Threads:
  - Create using the regular Java Thread Object
  - Android API provides thread helper classes:
    – Looper: for running a message loop with a thread
    – Handler: for processing messages
    – HandlerThread: for setting up a thread with a message loop

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1.6. Remote procedure calls

- Android RPCs = Binder mechanism
- No Sys V IPC due to in-kernel resource leakage
- Binder is a low-level functionality, not used as-is
- Instead: must define interface using Interface Definition Language (IDL)
- IDL fed to aidl Tool to generate Java interface definitions

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2. Framework Introduction

- UI

- Data storage

- Security/Permissions

- ... and much more ... :

  - Graphics

  - Audio and Video

  - Location and Maps

  - Bluetooth

  - NFC

2.1. UI

- Everything based on hierarchy of Views and ViewGroups (layouts)

- Declared in XML or dynamically through Java

- UI components:

  - Widgets

  - Event handlers

  - Menus

  - Dialogs

  - Notifications

  - ...

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2.2. Data storage

- **Shared preferences**

  - Private primitive key-pair values

- **Internal storage**

  - Private data on device memory

- **External storage**

  - Public data on shared external device (SD)

- **SQLite DB**

  - Private DB

- **Network connection**

  - Web-based storage (REST)

2.3. Security/Permissions

- Most security enforced at process level: UID, GID

- Permissions enforce restrictions on:

  - Per-process operations

  - Per-URI access

- Applications are sandboxed

- Specific permissions required to "exit" sandbox

- Decision to grant access based on:

  - Certificates

  - User prompts

- All permissions must be declared statically

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3. Native development

- What it can and cannot do
- Getting and installing the NDK
- Using the NDK
- Implementing fully native apps

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3.1. What it can and cannot do

- Useful for:
  - Porting existing body of code to Android
  - Developing optimized native apps, especially for gaming
- Provides:
  - Tools and build files to generate native code libraries from C/C++
  - Way to embed native libs into .apk
  - Set of stable (forward-compatible) native libs
  - Documentation, samples and tutorials
- Enables:
  - Calling native code from Java using JNI
  - Implementing fully native apps (since 2.3)
- Doesn't allow you to:
  - Compile traditional Linux/Unix apps as-is

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3.2. Getting and installing the NDK

- What's in the NDK?
  - Development tools
  - Stable native APIs system headers
  - Documentation - IMPORTANT
  - Samples
- Getting the NDK
  - http://developer.android.com/sdk/ndk/index.html
- Prerequisites
  - Windows, Mac or Linux
  - Complete SDK
  - make (GNU's) and awk
  - For Windows, Cygwin 1.7 or higher
- NDK set up:
  - Make sure prerequisites are installed
  - Download and install NDK

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3.3. Using the NDK

1. Place native code under <project>/jni/...

2. Create <project>/jni/Android.mk to describe native code to NDK

3. Optional: create <project>/jni/Application.mk for describing which natives sources are required by app

4. Build native code:

   · cd <project>

   · <ndk>/ndk-build

5. Compile app with SDK. Native code will be shared lib in .apk file.

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3.4. Implementing fully native apps

- Android 2.3 and up

- Native lifecycle management

- Still runs within context of dedicated Dalvik VM

- Can use JNI to call on Java functions

- Limited API:

  - Activity lifecycle management

  - Input events and sensors

  - Window management

  - Direct access to assets

- Make sure your activity is called: "android.app.NativeActivity"

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4.1. Overall Architecture - EL

Custom Application

Busybox

Libc
uClibc or eglibc or glibc

Linux Kernel
Process management, Memory management, Hardware support, ...
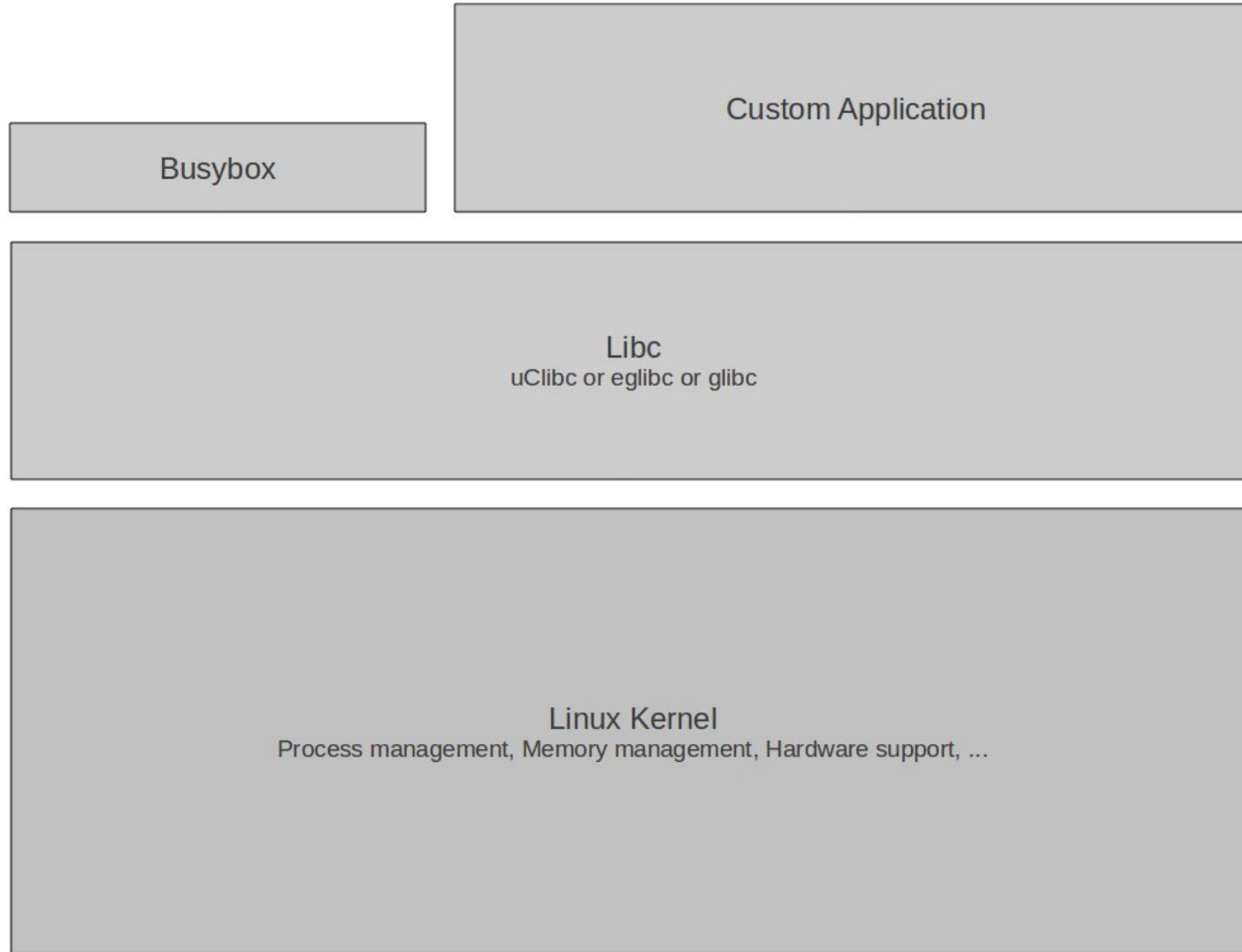
4.2. Overall Architecture - Android

Stock Android Apps

Launcher2	Phone	AlarmClock
Email	Settings	Camera
Gallery	Stk	Mms
Calendar	Browser	Bluetooth
Calculator	Contacts	...

Your Apps / Market Apps

App
API

Binder

System Server

Power Manager	Mount Service
Activity Manager	Notification Manager
Package Manager	Location Manager
Battery Service	Search Service
Window Manager	Wallpaper Service
Status Bar	Headset Observer
Clipboard Service	...

android.*

java.*
(Apache Harmony)

Android Runtime / Dalvik / Zygote

JNI

Libs
Bionic / OpenGL / WebKit / ...

Init / Toolbox

Native Daemons

Hardware
Support

Linux Kernel
Wakelocks / lowmem / binder / ashmem / ...

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5. System Startup

- Bootloader

- Kernel

- Init

- Zygote

- System Server

- Activity Manager

- Launcher (Home)

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5.1. Bootloader

- aosp/bootable/bootloader

  - Custom bootloader for Android

  - USB-based

  - Implements the "fastboot" protocol

  - Controlled via "fastboot" cli tool on host

- aosp/bootable/recovery

  - UI-based recovery boot program

  - Accessed through magic key sequence at boot

  - Usually manufacturer specific variant

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- Flash layout:

```
0x000003860000-0x000003900000 : "misc"
0x000003900000-0x000003e00000 : "recovery"
0x000003e00000-0x000004300000 : "boot"         ◄──────── Kernel
0x000004300000-0x00000c300000 : "system"        ◄──────── /system
0x00000c300000-0x0000183c0000 : "userdata"◄──────── /data
0x0000183c0000-0x00001dd20000 : "cache"         ◄──────── /cache
0x00001dd20000-0x00001df20000 : "kpanic"
0x00001df20000-0x00001df60000 : "dinfo"
0x00001df60000-0x00001dfc0000 : "setupdata"
0x00001dfc0000-0x00001e040000 : "splash1"
0x000000300000-0x000001680000 : "modem"
```

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5.2. Kernel

- Early startup code is very hardware dependent

- Initializes environment for the running of C code

- Jumps to the architecture-independent start_kernel() function.

- Initializes high-level kernel subsystems

- Mounts root filesystem

- Starts the init process

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5.3. Android Init

- Open, parses, and runs /init.rc:
  - Create mountpoints and mount filesystems
  - Set up filesystem permissions
  - Set OOM adjustments properties
  - Start daemons:
    - adbd
    - servicemanager (binder context manager)
    - vold
    - netd
    - rild
    - app_process -Xzygote (Zygote)
    - mediaserver
    - ...

5.4. Zygote, etc.

- Init:
  - app_process -Xzygote (Zygote)
- frameworks/base/cmds/app_process/app_main.cpp:
  - runtime.start("com.android.internal.os.Zygote", ...
- frameworks/base/core/jni/AndroidRuntime.cpp:
  - startVM()
  - Call Zygote's main()
- frameworks/base/core/java/com/android/internal/os/ZygoteInit.java:
  - ...

- preloadClasses()
- startSystemServer()
- ... magic ...
- Call SystemServer's run()

- frameworks/base/services/java/com/android/server/SystemServer.java:

  - Start **all** system services/managers
  - Start ActivityManager:
    - Send Intent.CATEGORY_HOME
    - Launcher2 kicks in

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6. Linux Kernel

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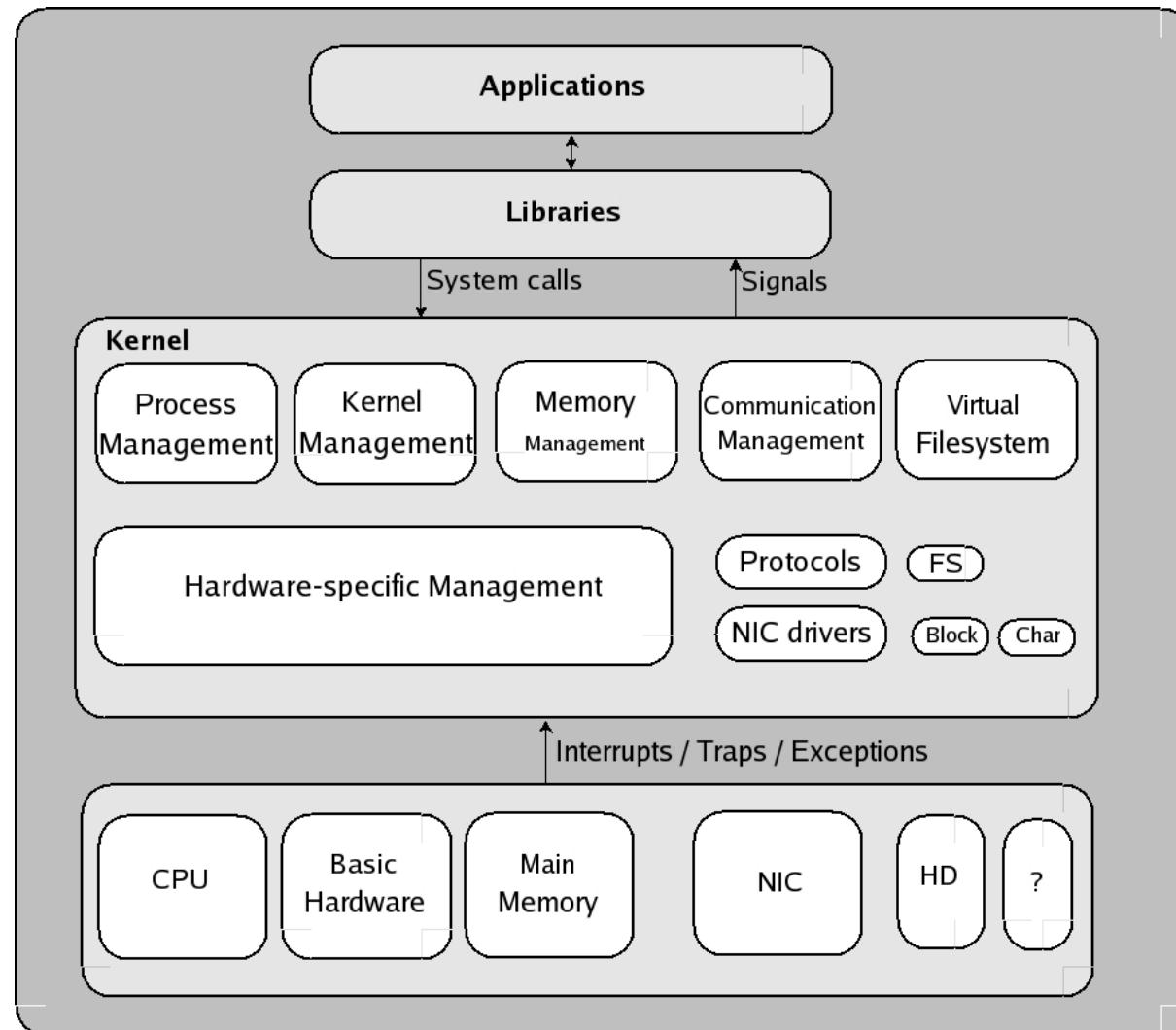
6.1. Androidisms

- Wakelocks

- lowmem handler

- Binder

- ashmem – Anonymous Shared Memory

- RAM console

- Logger

- ...

7. Hardware support

Bluetooth	BlueZ through D-BUS IPC (to avoid GPL contamination it seems)
GPS	Manufacturer-provided libgps.so
Wifi	wpa_supplicant
Display	Std framebuffer driver (/dev/fb0)
Keymaps and Keyboards	Std input event (/dev/event0)
Lights	Manufacturer-provided liblights.so
Backlight	
Keyboard	
Buttons	
Battery	
Notifications	
Attention	
Audio	Manufacturer-provided libaudio.so (could use ALSA underneath ... at least as illustrated in their porting guide)
Camera	Manufacturer-provided libcamera.so (could use V4L2 kernel driver underneath ... as illustrated in porting guide)
Power Management	"Wakelocks" kernel patch
Sensors	Manufacturer-provided libsensors.so
Accelerometer	
Magnetic Field	
Orientation	
Gyroscope	
Light	
Pressure	
Temperature	
Proximity	
Radio Layer Interface	Manufacturer-provided libril-<companyname>-<RIL version>.so

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8. Native User-Space

- Mainly
  - /data   => User data
  - /system => System components
- Also found:
  - /dev
  - /proc
  - /sys
  - /sbin
  - /mnt
  - /cache
  - Etc.

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- Libs:

  Bionic, SQLite, SSL, OpenGL|ES,

  Non-Posix: limited Pthreads support, no SysV IPC

- Toolbox

- Daemons:

  servicemanager, vold, rild, netd, adbd, ...

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9. Dalvik

- Sun-Java =

  Java language + JVM + JDK libs

- Android Java =

  Java language + Dalvik + Apache Harmony

- Target:

  - Slow CPU

  - Relatively low RAM

  - OS without swap space

  - Battery powered

- Now has JIT

9.1. Dalvik's .dex files

- JVM munches on ".class" files

- Dalvik munches on ".dex" files

- .dex file = .class files post-processed by "dx" utility

- Uncompressed .dex = 0.5 * Uncompressed .jar

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10. JNI – Java Native Interface

- Call gate for other languages, such as C, C++

- Equivalent to .NET's pinvoke

- Usage: include and call native code from App

- Tools = NDK ... samples included

- Check out *"JNI Programmer's Guide and Specification"* - freely available PDF

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11. System Server

Entropy Service
Power Manager
Activity Manager
Telephone Registry
Package Manager
Account Manager
Content Manager
System Content Providers
Battery Service
Lights Service
Vibrator Service
Alarm Manager
Init Watchdog
Sensor Service
Window Manager
Bluetooth Service

Device Policy
Status Bar
Clipboard Service
Input Method Service
NetStat Service
NetworkManagement Service
Connectivity Service
Throttle Service
Accessibility Manager
Mount Service
Notification Manager
Device Storage Monitor
Location Manager
Search Service
DropBox Service
Wallpaper Service

Audio Service
Headset Observer
Dock Observer
UI Mode Manager Service
Backup Service
AppWidget Service
Recognition Service
Status Bar Icons
DiskStats Service
ADB Settings Observer

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12. Calling on System Services

- Use getSystemService

- Ex: NotificationManager Object reference:

    String ns = Context.NOTIFICATION_SERVICE;

    NotificationManager mNotificationManager = (NotificationManager) \
    getSystemService(ns);

- Prepare your content

- Call on the object:

    mNotificationManager.notify(HELLO_ID, notification);

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13. ActivityManager

- Start new Activities, Services
- Fetch Content Providers
- Intent broadcasting
- OOM adj. maintenance
- Application Not Responding
- Permissions
- Task management
- Lifecycle management

- Ex. starting new app from Launcher:
  - onClick(Launcher)
  - startActivity(Activity.java)
  - *<Binder>*
  - ActivityManagerService
  - startViaZygote(Process.java)
  - *<Socket>*
  - Zygote

14. Binder

- CORBA/COM-like IPC

- Data sent through "parcels" in "transactions"

- Kernel-supported mechanism

- /dev/binder

- Check /proc/binder/*

- android.* API connected to System Server through binder.

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Service Manager (servicemanager)

Services List (*svclist):
- ActivityManager
- PowerManager
- WindowManager
- ...

binder_become_context_manager()

for(;;) "get service n"

do_find_service()

do_add_service()

A1

System Server (system_server)

ActivityManager:
- ...
- dump()
- ...

...

PowerManager:
- ...
- acquire()
- ...

addService()

A2

App(s)

Activity

WakeLock.acquire()

getService()

foo()

Service:
- ...
- foo()
- ...

B2 B1 C1

dumpsys

listServices()

checkService()

service->dump()

D1 D2 D3

ioctl(BINDER_SET_CONTEXT_MGR)
/* the one magic object */
#define BINDER_SERVICE_MANAGER ((void*) 0)

Binder Driver (/dev/binder)

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15. Stock AOSP Apps

/packages/apps

AccountsAndSettings
AlarmClock
Bluetooth
Browser
Calculator
Calendar
Camera
CertInstaller
Contacts
DeskClock
Email
Gallery
HTMLViewer

Launcher2
Mms
Music
PackageInstaller
Protips
Provision
QuickSearchBox
Settings
SoundRecorder
SpeechRecorder
Stk
VoiceDialer

/packages/providers

ApplicationProvider
CalendarProvider
ContactsProvider
DownloadProvider
DrmProvider
GoogleContactsProvider
MediaProvider
TelephonyProvider
UserDictionaryProvider

/packages/inputmethods

LatinIME
OpenWnn
PinyinIME

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Android Open Source Project

- Tools and location

- Content

- Building

- Build system

- Adding new applications

- Images

- Using adb

1. Tools and location

- Location:
  - http://android.googlesource.com
- Get "repo":

  $ curl https://dl-ssl.google.com/dl/googlesource/git-repo/repo > ~/bin/repo

  $ chmod a+x ~/bin/repo

- Fetch the AOSP:
  - Make sure you fetch a tagged release
  - Gingerbread:

    $ repo init -u https://android.googlesource.com/platform/manifest -b android-2.3.7_r1

    $ repo sync

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2. Content

bionic	C library replacement
bootable	Reference bootloader
build	Build system
cts	Compatibility Test Suite
dalvik	Dalvik VM
development	Development tools
device	Device-specific files and components
external	Copy of external projects used by AOSP
frameworks	System services, android.*, Android-related cmds, etc.
hardware	Hardware support libs
libcore	Apache Harmony
ndk	The NDK
packages	Stock Android apps, providers, etc.
prebuilt	Prebuilt binaries
sdk	The SDK
system	pieces of the world that are the core of the embedded linux platform at the heart of Android.

3. Building

- Requires 64-bit Ubuntu 10.04
- Packages required:

  $ sudo␣apt-get␣install␣build-essential␣libc6-dev␣\
  > ia32-libs␣lib32z1␣bison␣flex␣gperf␣git-core␣\
  > g++␣libc6-dev-i386␣libz-dev␣libx11-dev␣\
  > libstdc++6␣lib32ncurses5␣lib32ncurses5-dev␣\
  > g++-multilib

- Possibly fix a few symbolic links:

  $ sudo ln␣-s␣/usr/lib32/libstdc++.so.6␣/usr/lib32/libstdc++.so

  $ sudo ln␣-s␣/usr/lib32/libz.so.1␣/usr/lib32/libz.so

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- Set up build environment:

  $. build/envsetup.sh

  $ lunch

- Launch build and go watch tonight's hockey game:

  $ make -j2

- ... though you should check your screen at breaks ...

- Just launch emulator when it's done:

  $ emulator &

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- Some nice tricks:
  - See build/envsetup.sh for commands
  - Do use ccache (compiler cache):

    $ export USE_CCACHE=1

  - Use "lunch" from AOSP root to set env vars
    - You'll need that if you come back later and want to relaunch emulator from AOSP root:

    $. build/envsetup.sh

    $ lunch

    $ emulator

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4. Build system

- Non-Recursive
- "Modules" build predicated on Android.mk

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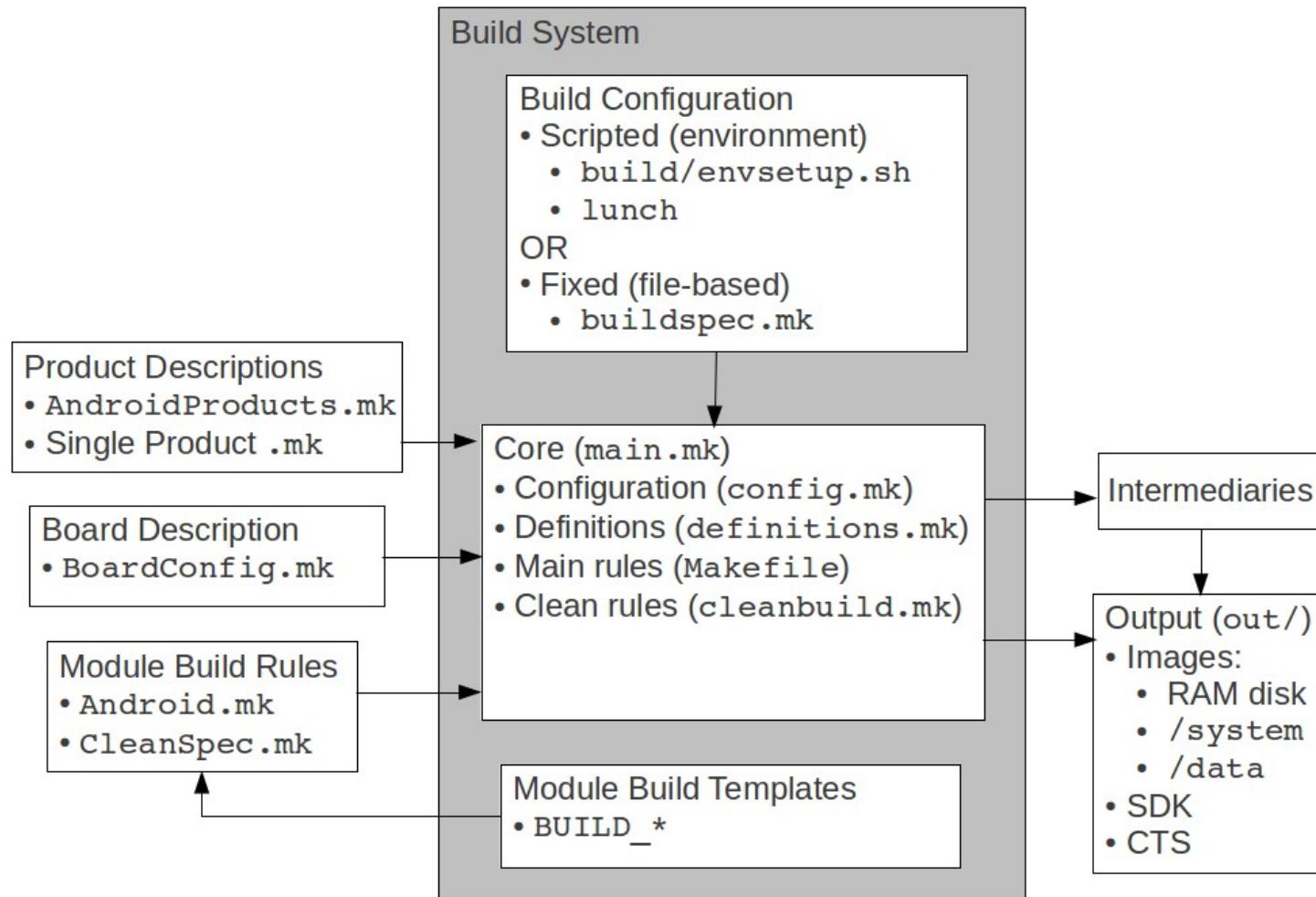
5. Adding new applications

- Add application in [aosp]/packages/apps

- Can use Eclipse to create initial version

- Copy Eclipse project to packages/apps

- Add an appropriate Android.mk file to project

- Add project to PRODUCT_PACKAGES in [aosp]/build/target/product/core.mk

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6. Images

- All output and build in [aosp]/out/

- Images at [aosp]/out/target/product/generic/:

  - ramdisk.img

  - system.img

  - userdata-qemu.img

- Kernel is in:

  - prebuilt/android-arm/kernel/kernel-qemu

- Emulator overrides:

  - -kernel

  - -initrd

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7. Using adb

- Can use to control/interface w/ running AOSP, including emulator.

- Shell:

    Host

    $ adb shell

    Target

    #
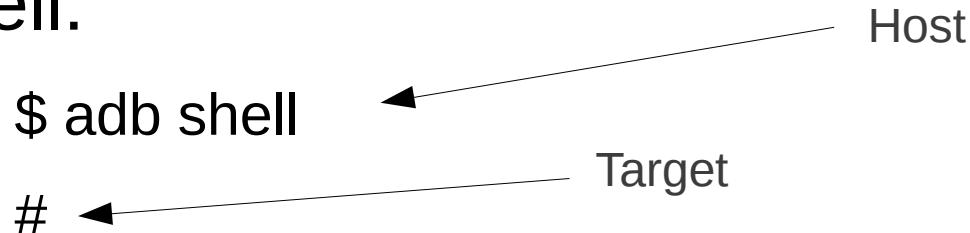
- Dumping the log:

    $ adb logcat

- Copying files to/from target:

    $ adb push foo /data/local

    $ adb pull /proc/config.gz

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Kernel basics

1. Selecting a kernel

2. Configuring the kernel

3. Compiling the kernel

4. Installing the kernel

5. Useful boot parameters

6. Kernel patches

1. Selecting a kernel

- Google:
  - http://android.googlesource.com
- Vanilla:
  - http://www.kernel.org
- ~~Either way ... you're screwed:~~
  - ~~Android kernel is a fork~~
  - ~~No resolution in sight~~
  - ~~**Cannot** use vanilla kernel as-is ... androidisms~~
- Kernel 3.3 has most Androidisms ... except:
  - Wakelocks

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2. Configuring the kernel
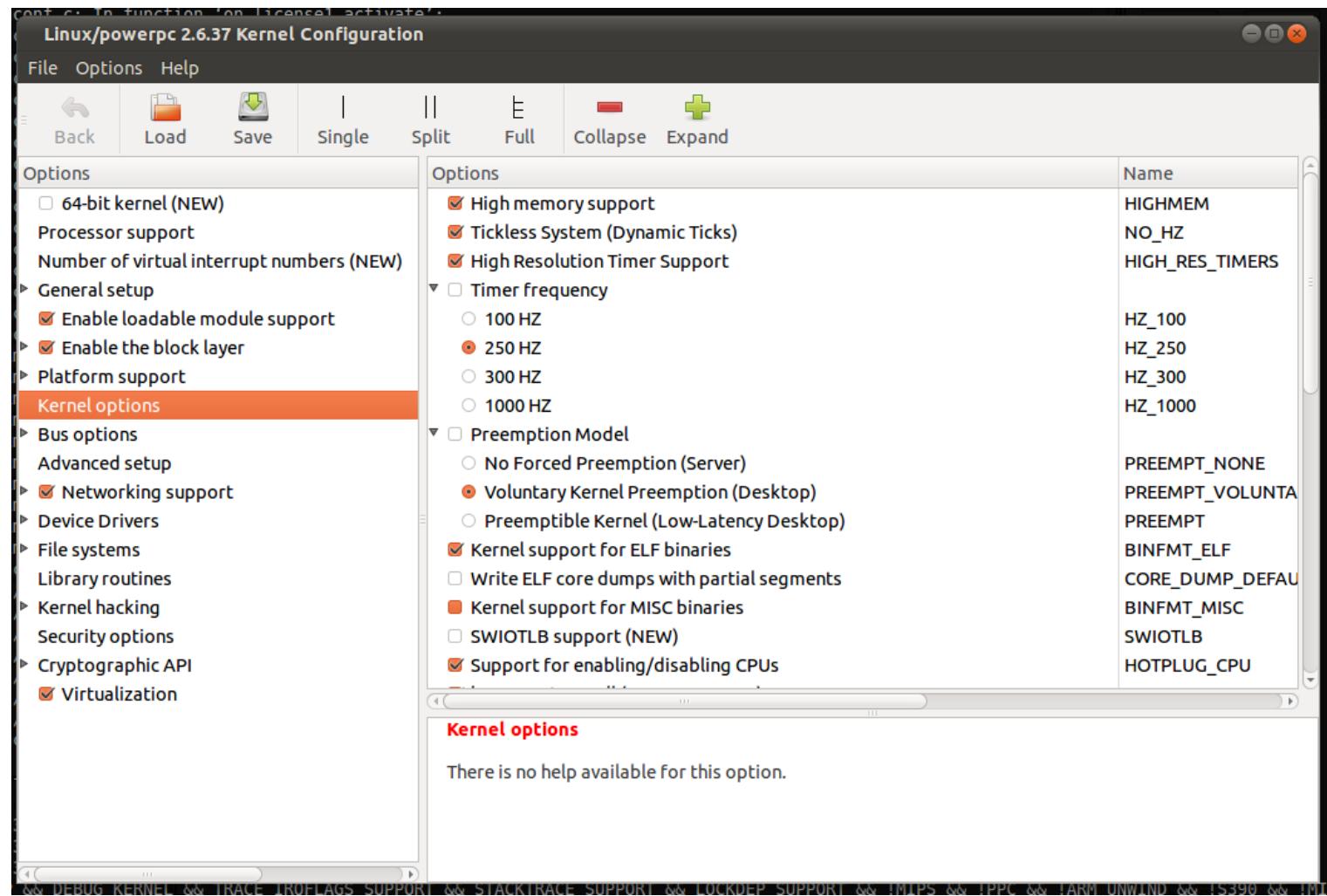
- **Main options:**
  - Processor support
  - General setup
  - Enable loadable module support
  - Enable the block layer
  - Platform support
  - Kernel options
  - Bus options
  - Advanced setup
  - Networking support
  - Device Drivers
  - File systems
  - Library routines
  - Kernel hacking
  - Security options
  - Cryptographic API

- Kernel architecture name (ARCH=):
  - x86　　=>　x86
  - ARM　=>　arm
  - PPC　=>　powerpc
  - mips　=>　mips
  - sh　　=>　sh
- Some options are visible only to certain archs

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- The fact that an option is displayed doesn't mean it's supported.
- The fact that an option isn't displayed doesn't mean it isn't supported.
- Configuration methods:
  - `make config`
  - `make oldconfig`
  - `make menuconfig`
  - `make xconfig`
- All config methods generate a .config file

- Configs will also generate headers & symlinks
- Set up temporary env. var. for cross-building:

```
$ export TARGET=[your_aosp]/prebuilt/linux-x86/toolchain/arm-
  eabi-4.4.0/bin/arm-eabi
```

- To start configuration menu for your target:

```
$ make ARCH=arm CROSS_COMPILE=${TARGET}- menuconfig
```

- Some items can be configured as modules and loaded dynamically at runtime.
- Once the configuration is done, quit the menu and save your configuration. This will create a .config file.
- Some targets have preset configurations:

```
$ make ARCH=arm CROSS_COMPILE=${TARGET}- \
> davinci_all_defconfig
```

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- Can use the menus provided by menuconfig and xconfig to load and save various configurations.
- Simplest way to manipulate configurations: copy the .config files by hand.
- To reuse an old configuration, simply copy the .config back to the kernel's tree and:

  ```
  $ make ARCH=arm CROSS_COMPILE=${TARGET}- oldconfig
  ```
- Place all your .config files in your ${PRJROOT}/kernel directory for easy access.
- Rename your .config files using meaningful names: 2.6.37.config, 2.6.37-frame-buf.config, ...

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3. Compiling the kernel

1. Building the kernel:

   - Command:
   ```
   $ make ARCH=arm CROSS_COMPILE=${TARGET}- zImage
   ```
   - Generates a kernel image compressed via gzip
   - zImage may not be valid target. Other targets include: vmlinux, bzImage, uImage, cuImage, …
   - Use "make ARCH=... help" to find out valid targets
   - ARCH variable indicates which architecture subdirectory is to be used.
   - CROSS_COMPILE is used to form the name of the tools. For example, `$(CROSS_COMPILE)gcc` becomes `arm-linux-gcc`. Hence the trailing "-".

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2.Building the modules:

```
$ make ARCH=arm CROSS_COMPILE=${TARGET}- modules
```

- **<u>IF YOU NEED TO</u>** restore kernel tree to distribution state:

```
$ make ARCH=arm CROSS_COMPILE=${TARGET}- distclean
```

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4. Installing the kernel[1]

- Managing multiple kernel images:

  - Images in ${PRJROOT}/images must be properly identified.

  - For each kernel, there are 4 files to put in ${PRJROOT}/images:

    - The uncompressed image   => `vmlinux`

    - The compressed image   => depends on arch

    - The kernel symbols   => `System.map`

    - The kernel configuration file => `.config`

  - Compressed image is *usually* in the arch/YOUR_ARCH/boot directory.

1. This is for **future** reference. $PRJROOT is undefined at this point

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- See the exercise set for target image we are using.

- Location of images can be seen by looking at arch/YOUR_ARCH/Makefile

- Images placed in ${PRJROOT}/images must follow same naming convention as .config file:

```
$ cp arch/arm/boot/zImage \
> ${PRJROOT}/images/zImage-2.6.37
$ cp System.map ${PRJROOT}/images/System.map-2.6.37
$ cp vmlinux ${PRJROOT}/images/vmlinux-2.6.37
$ cp .config ${PRJROOT}/images/2.6.37.config
```

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- Installing the kernel modules:
  - Must install modules in directory following the previously adopted naming convention:
    ```
    $ make ARCH=arm CROSS_COMPILE=${TARGET}- \
    > INSTALL_MOD_PATH=${PRJROOT}/images/modules-2.6.37 \
    > modules_install
    ```
  - `INSTALL_MOD_PATH` is prepended to the default /lib/modules. Hence, modules installed in: ${PRJROOT}/images/modules-2.6.37/lib/modules

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Embedded Linux Root FS

1. Rationale
2. Architecture
3. Tools
4. Embedded Linux Workspace
5. Basic root filesystem structure
6. Libraries
7. Kernel modules
8. Device files
9. Main system applications
10. Auto-generating filesystems

1. Rationale

- Port existing Linux apps

- Create glibc-based apps to coexist with Android's Bionic-based user-space

- Avoid having to deal with AOSP's build system

- Avoid having having to deal w/ Bionic's quirks and limitations

- Benefit from standard GNU world

2. Architecture

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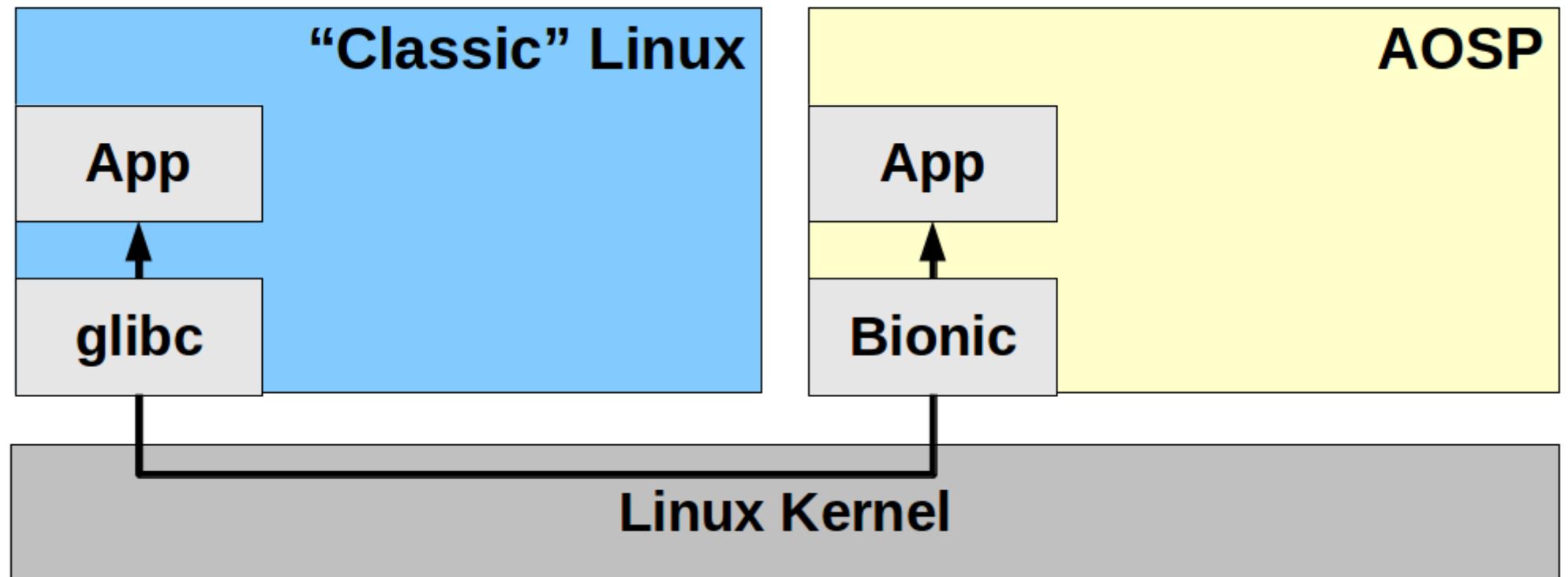
Host

AOSP (bionic)

build/
system/
frameworks/
packages/
external/

PRJROOT (glibc)

sysapps/
rootfs/
build-tools/
.../

Kernel

Target

- ramdisk.img   => /
  - /bin
  - /lib
- system.img   => /system
- userdata.img   => /data

Kernel

3. Tools

- GNU cross-development toolchain:
  - gcc - compiler
  - as - assembler
  - ld - linker
  - gdb/gdbserver - debugger
  - etc.
- C library: uClibc, eglibc or glibc

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4. Embedded Linux Workspace

- Need to organize the components used during cross-platform development. Workspace layout:

bootldr:	target bootloader (s)
build-tools:	toolchain build packages and sources
debug:	debugging tools
doc:	project documentation
images:	binary images ready to be used on target
kernel:	sources and build directories for target kernels
project:	your own custom code for the target
rootfs:	root filesystem as seen on the target
sysapps:	sources for target's system applications
tmp:	temporary data and experiments
tools:	toolchain and all other tools required to build software for the target.

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4.1. Workspace env. vars. script

- Complete workspace script (devex)

```
export PROJECT=emblinux
export PRJROOT=/home/karim/${PROJECT}
export TARGET=arm-none-linux-gnueabi
export PATH=${PATH}:[CODESOURCERY_DIR]/bin
cd $PRJROOT
```

- To use this script:

  ```
  $ . devex
  ```

- Possible values for $TARGET:
  - ARM: arm-linux, arm-unknown-linux-gnueabi
  - MIPS: mips-linux, mipsel-unknown-linux-gnu
  - I386:   i386-linux, i586-geode-linux-uclibc

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5. Basic root filesystem structure

- Unix FS structured for multi-user systems
- Some directories not necessary for embedded
- Filesystem Hierarchy Standard (FHS):
  - /bin   =>   Essential user binaries
  - /boot   =>   Bootloader and kernel images
  - /dev   =>   Device files
  - /etc   =>   System configuration
  - /home   =>   User home directories
  - /lib   =>   Essential shared libs and kernel modules
  - /mnt   =>   Temporary mount point
  - /opt   =>   Add-on software packages
  - /sbin   =>   Essential system binaries
  - /tmp   =>   Temporary files
  - /usr   =>   Secondary hierarchy (mostly user apps)
  - /var   =>   Variable data generated by daemons

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- Non-essential multi-user dirs:
  - /home, /mnt, /opt, /root
- Depends on bootloader:
  - /boot
- ***Traditionally*** "essential":
  - /bin, /dev, /etc, /lib, /proc, /sbin, /usr, /tmp, /var
- Careful with "/etc", Android needs it to point to "/system/etc" for Dbus config ... Just hack it.
- Contain their own hierarchy:
  - /usr, /var

- What are all these binaries directories for?
  - /bin   =>   Essential binaries for user and admin
  - /sbin   =>   Essential binaries for admin
  - /usr/bin =>   Non-essential user and admin binaries
  - /usr/sbin=>   Non-essential admin binaries
- What are all those libraries directories for?
  - /lib   =>   Essential system libraries
  - /usr/lib   =>   Non-essential libraries
- The kernel does not force FS layout. Layout is "universally" agree upon (i.e. FHS.)

- To start working on rootfs:
  ```
  $ cd ${PRJROOT}/rootfs
  ```
- Create core rootfs directories:
  ```
  $ mkdir bin lib sbin usr var
  ```
- Create the /usr hierarchy:
  ```
  $ mkdir usr/{bin,lib,sbin}
  ```
- Create the /var hierarchy:
  ```
  $ mkdir var/{lib,lock,log,run,tmp}
  $ chmod 1777 var/tmp
  ```

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6. Libraries

1. glibc
2. uClibc

6.1. glibc

- glibc components:
  - Actual shared libraries:
    - Format: libLIB_NAME-GLIBC_VER.so
    - Examples: libm-2.3.2.so, libc-2.3.2.so
  - Major revision version symbolic links:
    - Format: libLIB_NAME.so.MAJOR_REV_VER
    - Examples: libdl.so.2, libc.so.6
  - Version-independent symbolic links to the major revision version symbolic links:
    - Format: libLIB_NAME.so
    - Examples: libdl.so, libm.so
  - Static library archives:
    - Format: libLIB_NAME.a
    - Examples: libdl.a, libm.a

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- For target, need:
  - The actual shared libs
  - The major revision version symbolic links
- Also need dynamic linker:
  - Actual linker: ld-GLIBC_VER.so
  - Symbolic link to linker:
    - x86, ARM, SH, m68k   => ld-linux.so.MAJOR_REV_VER
    - MIPS, PPC   => ld.so.MAJOR_REV_VER
- Must determine exact library components required.
- BELS table 6.2 contains complete list

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- Most important components:
    - ld   =>   the dynamic linker
    - libc   =>   the C library
    - libm =>   the math library
    - libdl =>   the shared objects manipulation library
- Must determine exact dependencies of your applications.
- Native `ldd` is not cross-platform-capable
- Can use `readelf` or `uclibc-ldd`:

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- ## Using readelf:
  ```
  $ arm-linux-readelf -a ${PRJROOT}/rootfs/bin/busybox \
  > | grep "Shared library"
   0x00000001 (NEEDED)                 Shared library: [libc.so.0]
  ```
- ## Using uclibc-ldd:
  ```
  $ arm-uclibc-ldd ${PRJROOT}/rootfs/bin/busybox
  libc.so.0 => /home/karim/example-sys/tools/uclibc/lib/libc.so.0
  /lib/ld-uClibc.so.0 => /lib/ld-uClibc.so.0
  ```
- ## Copying important libraries to target rootfs:
  ```
  $ cd ${TARGET_PREFIX}/lib
  $ for file in libc libcrypt libdl libm \
  > libpthread libresolv libutil
  > do
  > cp $file-*.so ${PRJROOT}/rootfs/lib
  > cp -d $file.so.[*0-9] ${PRJROOT}/rootfs/lib
  > done
  $ cp -d ld*.so* ${PRJROOT}/rootfs/lib
  ```

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- Copying all libraries:

```
$ cp -d [CODESOURCERY_DIR]/arm-none-linux-gnueabi/libc/lib/* \
> ${PRJROOT}/rootfs/lib
```

- Stripping all target libraries for space efficiency:

```
$ arm-none-linux-gnueabi-strip ${PRJROOT}/rootfs/lib/*.so*
```

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6.2. uClibc

- Same naming conventions as glibc
- Implements most of the glibc components:
  - ld, libc, libcrypt, libdl, libm, libpthread, libresolv, libutil.
- uClibc libraries can coexist with glibc libraries in target's /lib directory.
- Copying important libraries to target rootfs:
  ```
  $ cd ${PREFIX}/uclibc/lib
  $ for file in libuClibc ld-uClibc libc libdl \
  > libcrypt libm libresolv libutil
  > do
  > cp $file-*.so ${PRJROOT}/rootfs/lib
  > cp -d $file.so.[*0-9] ${PRJROOT}/rootfs/lib
  > done
  ```

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- Copying all uClibc components:

```
$ cd ${PREFIX}/uclibc/lib
$ cp *-*.so ${PRJROOT}/rootfs/lib
$ cp -d *.so.[*0-9] ${PRJROOT}/rootfs/lib
```

- No need to strip uClibc libraries, they are stripped by the uClibc build script.

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7. Kernel modules

- Kernel modules are located in /lib/modules, so they must be installed in ${PRJROOT}/rootfs/lib/modules.
- Copying modules built earlier:
  ```
  $ cp -a ${PRJROOT}/images/modules-2.6.37/* \
  > ${PRJROOT}/rootfs
  ```
- Module loading customization (/etc/modprobe.conf or /etc/modprobe.d/)

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8. Device files

- All devices in Linux are seen as files (except Ethernet interfaces.)
- Typical workstation distros use udev
- Keep a copy of Documentation/devices.txt handy
- See BELS table 6.3 for core set of /dev entries
- Properties of each /dev node:
    - Filename (node name)
    - Type (char / block)
    - Major number (What type of device?)
    - Minor number (Which instance of the device?)
    - Permission bits
- No need to create these entries since AOSP does it for us

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9. Main system applications

- Unix systems rely on a common set of commands

- Standard distros have one binary per command

- May compile each relevant command one-by-one or use packages that provide many commands in a single binary:

    1. Busybox
    2. Distro

9.1. BusyBox

- Main package used in embedded Linux to provide core set of Unix commands: busybox.net

[, [[, acpid, add-shell, addgroup, adduser, adjtimex, arp, arping, ash, awk, base64, basename, beep, blkid, blockdev, bootchartd, brctl, bunzip2, bzcat, bzip2, cal, cat, catv, chat, chattr, chgrp, chmod, chown, chpasswd, chpst, chroot, chrt, chvt, cksum, clear, cmp, comm, cp, cpio, crond, crontab, cryptpw, cttyhack, cut, date, dc, dd, deallocvt, delgroup, deluser, depmod, devmem, df, dhcprelay, diff, dirname, dmesg, dnsd, dnsdomainname, dos2unix, du, dumpkmap, dumpleases, echo, ed, egrep, eject, env, envdir, envuidgid, ether-wake, expand, expr, fakeidentd, false, fbset, fbsplash, fdflush, fdformat, fdisk, fgconsole, fgrep, find, findfs, flock, fold, free, freeramdisk, fsck, fsck.minix, fsync, ftpd, ftpget, ftpput, fuser, getopt, getty, grep, gunzip, gzip, halt, hd, hdparm, head, hexdump, hostid, hostname, httpd, hush, hwclock, id, ifconfig, ifdown, ifenslave, ifplugd, ifup, inetd, init, insmod, install, ionice, iostat, ip, ipaddr, ipcalc, ipcrm, ipcs, iplink, iproute, iprule, iptunnel, kbd_mode, kill, killall, killall5, klogd, last, length, less, linux32, linux64, linuxrc, ln, loadfont, loadkmap, logger, login, logname, logread, losetup, lpd, lpq, lpr, ls, lsattr, lsmod, lspci, lsusb, lzcat, lzma, lzop, lzopcat, makedevs, makemime, man, md5sum, mdev, mesg, microcom, mkdir, mkdosfs, mke2fs, mkfifo, mkfs.ext2, mkfs.minix, mkfs.vfat, mknod, mkpasswd, mkswap, mktemp, modinfo, modprobe, more, mount, mountpoint, mpstat, mt, mv, nameif, nbd-client, nc, netstat, nice, nmeter, nohup, nslookup, ntpd, od, openvt, passwd, patch, pgrep, pidof, ping, ping6, pipe_progress, pivot_root, pkill, pmap, popmaildir, poweroff, powertop, printenv, printf, ps, pscan, pwd, raidautorun, rdate, rdev, readahead, readlink, readprofile, realpath, reboot, reformime, remove-shell, renice, reset, resize, rev, rm, rmdir, rmmod, route, rpm, rpm2cpio, rtcwake, run-parts, runlevel, runsv, runsvdir, rx, script, scriptreplay, sed, sendmail, seq, setarch, setconsole, setfont, setkeycodes, setlogcons, setsid, setuidgid, sh, sha1sum, sha256sum, sha512sum, showkey, slattach, sleep, smemcap, softlimit, sort, split, start-stop-daemon, stat, strings, stty, su, sulogin, sum, sv, svlogd, swapoff, swapon, switch_root, sync, sysctl, syslogd, tac, tail, tar, tcpsvd, tee, telnet, telnetd, test, tftp, tftpd, time, timeout, top, touch, tr, traceroute, traceroute6, true, tty, ttysize, tunctl, udhcpc, udhcpd, udpsvd, umount, uname, unexpand, uniq, unix2dos, unlzma, unlzop, unxz, unzip, uptime, usleep, uudecode, uuencode, vconfig, vi, vlock, volname, wall, watch, watchdog, wc, wget, which, who, whoami, xargs, xz, xzcat, yes, zcat, zcip

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- Download BusyBox (1.18.3) to your $ {PRJROOT}/sysapps directory and extract it there.

- Move to the directory for the rest of the setup:

```
$ cd ${PRJROOT}/sysapps/busybox-1.18.3
```

- Configuration of BusyBox's options:

```
$ make menuconfig
```

130
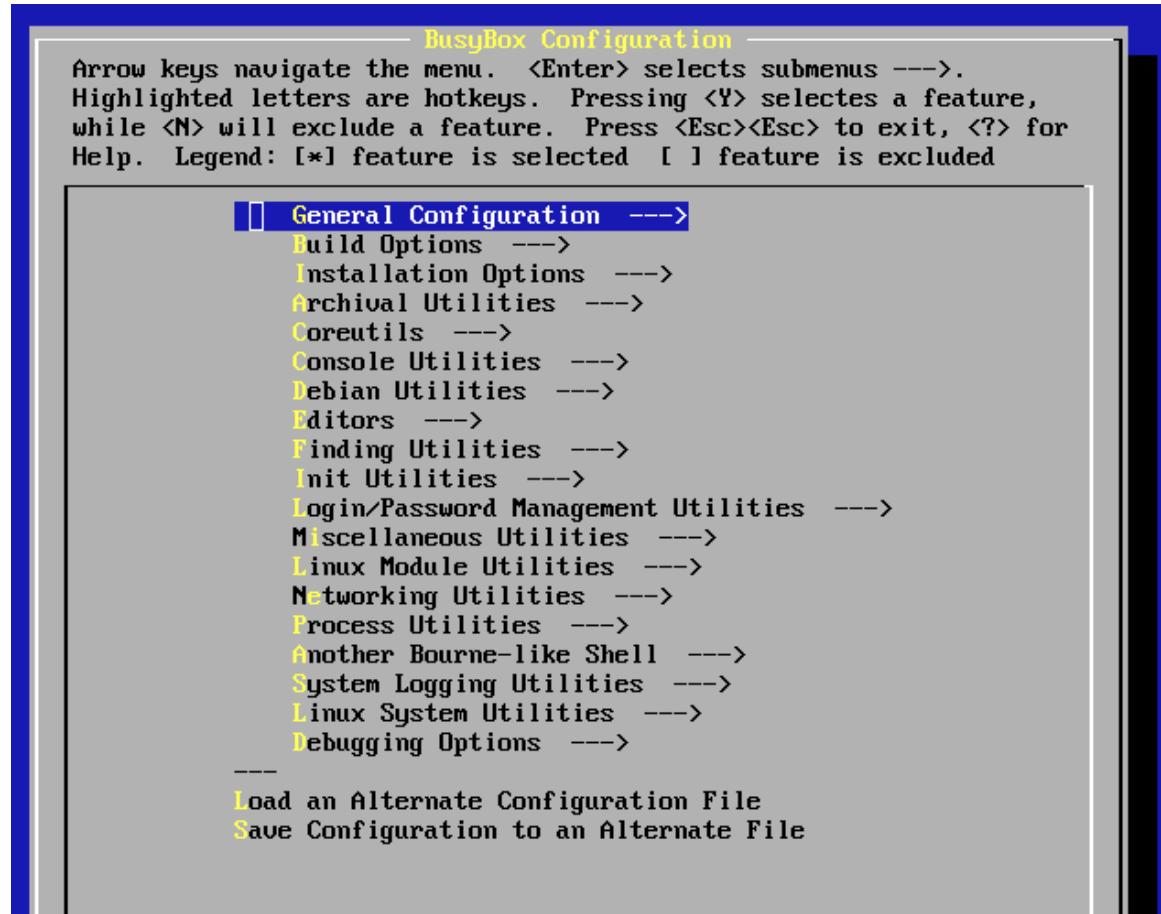
- "Busybox Settings":
  - "Build Options" -> Cross-compiler prefix:

    `${TARGET}-`

  - "Installation Options" -> Installation prefix:

    `${PRJROOT}/rootfs`

- Build:

  `$ make`

- Install:

  `$ make install`

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- Only one binary has been installed: /bin/busybox
- All commands are symbolic links to /bin/busybox
- Determining the command issued done through main's `argv[]` and `argc`.
- Creating arbitrary links doesn't work
- BusyBox can be told to create hard-links
- Full command doc on web and in package
- Customizing the paths for the various shells:

```
# Set path
PATH=/bin:/sbin:/usr/bin:/usr/sbin
export PATH
```

10. Auto-generating FSes/distros

- Yocto

- Buildroot

- PTXdist

- OpenWRT

- LTIB

- OpenEmbedded

- Gentoo

Native Android User-Space

- Filesystem layout

- Bionic

- Toolbox

- Init

- Native daemons

- Power tools

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1. Filesystem layout

- /acct => Control Group mount point (Documentation/cgroups.txt)
- /cache => cache flash partition
- /d => Symlink to /sys/kernel/debug
- /data => Android's "/data" filesystem
- /dev => Device nodes
- /etc => Symlink to /system/etc
- /mnt => Temporary mount point
- /proc => procfs
- /root => unused
- /sbin => eventd and adbd
- /sdcard => SD card mountpoint
- /sys => sysfs
- /system => Android's "/system" filesystem
- /vendor => Symlink to /system/vendor

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1.1. /system

- /app => Stock apps installed
- /bin => Native binaries and daemons
- /etc => Configuration files
- /fonts => TTFs
- /framework => Android framework .jar files
- /lib => Native libraries
- /usr => Miniature "/usr"
- /xbin => Extra binaries

1.2. /data

- /anr   => ANR traces
- /app   => App install location
- /app-private   => Protected apps
- /backup   => For Backup Manager
- /dalvik-cache   => Dalvik DEX cache
- /data   => App data
- /dontpanic   => Last panic output (console + threads) for "dumpstate"
- /local   => Shell-writable space
- /misc   => Misc. data (wifi, vpn, bluetooth, ...)
- /property   => Persistent system properties (country, lang., ...)
- /secure   => Secure Android data available
- /system   => System data

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2. Bionic

- In aosp:
  - /bionic
- In filesystem:
  - /system/lib
- Provides:
  - libc
  - libm
  - libdl
  - libstd++
  - libthread_db
  - linker

3. Toolbox

- In aosp:
  - /system/core/toolbox
- In filesystem:
  - /system/bin/toolbox
- Provides

  alarm date getevent insmod ls mv powerd renice schedtop smd top dd getprop ioctl lsmod nandread printenv rm sendevent start umount cat hd ionice lsof netstat ps rmdir setconsole stop uptime chmod df id kill mkdir newfs_msdos r rmmod setkey sync vmstat chown dmesg ifconfig ln readtty rotatefb setprop syren watchprops cmp exists iftop log mount notify reboot route sleep wipe

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4. Init

- In aosp:
  - /system/core/init
- In filesystem:
  - /init
- Relies on:
  - /init.rc
  - /init.[board].rc
  - /ueventd.rc
  - /ueventd.[board].rc
  - /system/etc/init.[board].sh

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5. Native daemons

- servicemanager
- vold
- rild
- netd
- adbd
- Installd

5.1. servicemanager

- In aosp:
    - /frameworks/base/cmds/servicemanager/
- In filesystem:
    - /system/bin/
- Provides:
    - Context management for binder
    - Service index for entire system

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5.2. vold

- In aosp:
  - /system/vold/
- In filesystem:
  - /system/bin/
- Provides:
  - Volume mounter
  - Auto-mount
  - Auto-format mounted devices

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5.3. rild

- In aosp:
  - /hardware/ril/mock-ril/
- In filesystem:
  - /system/bin/
- Provides:
  - "Radio Interface Layer" to phone hardware

5.4. netd

- In aosp:
  - /system/netd/
- In filesystem:
  - /system/bin/
- Provides:
  - Management of aspects of networking
  - Interfaces with Network Management service

5.5. adbd

- In aosp:
  - /system/core/adb/
- In filesystem:
  - /sbin
- Provides:
  - Interfaces with host "adb" command
  - Remote debugging capabilities
  - Access to shell
  - Package install/uninstall
  - ... see "adb help" on host for full detail

5.6. installd

- In aosp:
  - /frameworks/base/cmds/installd
- In filesystem:
  - /system/bin/
- Provides:
  - Package install/uninstall
  - Sanity checks and verifications
 - Interfaces with Package Manager service

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6. Power tools

- dumpstate
- dumpsys
- service
- logcat
- am

System Services

- Architecture
- Services run by System Server
- Observing the System Server
- Calling on system services
- Inside a few system services
- Creating your own system service

1. Architecture

System Services

System Server

Java-built Services

Power Manager	Mount Service
Activity Manager	Notification Manager
Package Manager	Location Manager
Battery Service	Search Service
Window Manager	Wallpaper Service
Status Bar	Headset Observer
Clipboard Service	...

JNI ....

Native Methods for
Java-built Services

C-built Services

Sensor Service
Surface Flinger

Media Service

Audio Flinger
Media Player Service
Camera Service
Audio Policy Service

Includes:
• StageFright
• Audio effects
• DRM framework

Hardware Abstraction Layer

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2. Services run by the System Server

Entropy Service
Power Manager
Activity Manager
Telephone Registry
Package Manager
Account Manager
Content Manager
System Content Providers
Battery Service
Lights Service
Vibrator Service
Alarm Manager
Init Watchdog
Sensor Service
Window Manager
Bluetooth Service

Device Policy
Status Bar
Clipboard Service
Input Method Service
NetStat Service
NetworkManagement Service
Connectivity Service
Throttle Service
Accessibility Manager
Mount Service
Notification Manager
Device Storage Monitor
Location Manager
Search Service
DropBox Service
Wallpaper Service

Audio Service
Headset Observer
Dock Observer
UI Mode Manager Service
Backup Service
AppWidget Service
Recognition Service
Status Bar Icons
DiskStats Service
ADB Settings Observer

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2.1. Some stats

- frameworks/base/services/java/com/android/server:
  - 3.5 M
  - ~100 files
  - 85 kloc
- Activity manager:
  - 920K
  - 30+ files
  - 20 kloc

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3. Observing the System Services

- logcat
- dumpsys

3.1. logcat

- **Find the System Server's PID**

    $ adb shell ps | grep system_server

    system   63   32   120160 35408 ffffffff afd0c738 S system_server

- Look for its output:

    $ adb logcat | grep "63)"

```
...
D/PowerManagerService(   63): bootCompleted
I/TelephonyRegistry(   63): notifyServiceState: 0 home Android Android 310260  UMTS CSS not supp...
I/TelephonyRegistry(   63): notifyDataConnection: state=0 isDataConnectivityPossible=false reason=null
interfaceName=null networkType=3
I/SearchManagerService(   63): Building list of searchable activities
I/WifiService(   63): WifiService trying to setNumAllowed to 11 with persist set to true
I/ActivityManager(   63): Config changed: { scale=1.0 imsi=310/260 loc=en_US touch=3 keys=2/1/2 nav=3/1 ...
I/TelephonyRegistry(   63): notifyMessageWaitingChanged: false
I/TelephonyRegistry(   63): notifyCallForwardingChanged: false
I/TelephonyRegistry(   63): notifyDataConnection: state=1 isDataConnectivityPossible=true reason=simL...
I/TelephonyRegistry(   63): notifyDataConnection: state=2 isDataConnectivityPossible=true reason=simL...
D/Tethering(   63): MasterInitialState.processMessage what=3
I/ActivityManager(   63): Start proc android.process.media for broadcast
com.android.providers.downloads/.DownloadReceiver: pid=223 uid=10002 gids={1015, 2001, 3003}
I/RecoverySystem(   63): No recovery log file
W/WindowManager(   63): App freeze timeout expired.
...
```

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3.2. dumpsys

```
Currently running services:
  SurfaceFlinger
  accessibility
  account
  activity
  alarm
  appwidget
  audio
  backup
...
  wifi
  window
-------------------------------------------------------------------------------
DUMP OF SERVICE SurfaceFlinger:
+ Layer 0x396b90
    z=   21000, pos=(   0,   0), size=( 480, 800), needsBlending=1, needsDithering=1, invalidat ...
0]
    name=com.android.launcher/com.android.launcher2.Launcher
    client=0x391e48, identity=6
    [ head= 1, available= 2, queued= 0 ] reallocMask=00000000, inUse=-1, identity=6, status=0
    format= 1, [480x800:480] [480x800:480], freezeLock=0x0, dq-q-time=53756 us
...
```

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4. Calling on System Services

- Use getSystemService

- Ex: NotificationManager Object reference:

  String ns = Context.NOTIFICATION_SERVICE;

  NotificationManager mNotificationManager = (NotificationManager) \
  getSystemService(ns);

- Prepare your content

- Call on the object:

  mNotificationManager.notify(HELLO_ID, notification);

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5. Inside a few System Services

- Get the AOSP ... repo, etc.

- Tricks:

  - Import into Eclipse and collapse methods

  - Use reverse-engineering tools:

    – Imagix

    – Rationale

    – Lattix

    – Scitools

    – ...

- Be patient, this isn't documented anywhere ...

5.1. ActivityManager

- Start new Activities, Services
- Fetch Content Providers
- Intent broadcasting
- OOM adj. maintenance
- Application Not Responding
- Permissions
- Task management
- Lifecycle management

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- Ex. starting new app from Launcher:
  - onClick(Launcher)
  - startActivity(Activity.java)
  - *<Binder>*
  - ActivityManagerService
  - startViaZygote(Process.java)
  - *<Socket>*
  - Zygote

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5.2. Package Manager

- 10 kloc

- 450 K

- Installation / removal

- Permissions

- Intent resolution (also IntentResolver.java)

- Called by Activity Manager

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5.3. Window Manager

- Main thread

- Window manipulation

- Wallpaper handling

- Orientation

- Focus

- Layering

- Input event management

5.4. Notification Manager

- Toasts

- Notifications

- Sound playback (see NotificationPlayer.java)

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5.5. Power Manager

- Wakelocks

- Sleep

- Brightness

- Lock

5.6. Network Management Service

- Talks to "netd" /system/netd
- Interface configuration
- Tethering
- DNS

5.7. Mount Service

- Mount / Unmount

- Format

- USB mass storage

- OBB

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5.8. Location Manager

- Manage location providers
- getBestProvider()
- Proximity alerts
- Last known location

5.9. Status Bar Manager

- Expand / collapse

- Icon visibility

- Reveal callbacks

- Callbacks for notification manager

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5.10. Backup Manager

- Enable / disable

- Transport management

- backupNow()

- ...

6. Creating your own System Service

- Add your code to: frameworks/base/services/java/com/android/server/

- Have the SystemServer.java init+reg. your service

- Define hardware API for apps

- Expose through:

  - frameworks/base/core/java/android/os/[server].aidl

- Call on native "driver" code through JNI

- Implement or connect to appropriate driver

- Create an app that calls on service

- May need to create new SDK ...

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```java
package com.android.server;

import android.content.Context;
import android.os.Handler;
import android.os.IOpersysService;
import android.os.Looper;
import android.os.Message;
import android.os.Process;
import android.util.Log;

public class OpersysService extends IOpersysService.Stub {
    private static final String TAG = "OpersysService";
    private OpersysWorkerThread mWorker;
    private OpersysWorkerHandler mHandler;
    private Context mContext;

    public OpersysService(Context context) {
        super();
        mContext = context;
        mWorker = new OpersysWorkerThread("OpersysServiceWorker");
        mWorker.start();
        Log.i(TAG, "Spawned worker thread");
    }

    public void setValue(int val) {
        Log.i(TAG, "setValue " + val);
        Message msg = Message.obtain();
        msg.what = OpersysWorkerHandler.MESSAGE_SET;
        msg.arg1 = val;
        mHandler.sendMessage(msg);
    }
```

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```java
private class OpersysWorkerThread extends Thread{
public OpersysWorkerThread(String name) {
    super(name);
}

public void run() {
    Looper.prepare();
    mHandler = new OpersysWorkerHandler();
    Looper.loop();
    }
}

private class OpersysWorkerHandler extends Handler {
private static final int MESSAGE_SET = 0;

@Override
public void handleMessage(Message msg) {
    try {
    if (msg.what == MESSAGE_SET) {
        Log.i(TAG, "set message received: " + msg.arg1);
        }
    }
    catch (Exception e) {
    // Log, don't crash!
    Log.e(TAG, "Exception in OpersysWorkerHandler.handleMessage:", e);
        }
    }
}
}
```

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6.2. IOpersysService.aidl

```
package android.os;
interface IOpersysService {
/**
* {@hide}
*/
void setValue(int val);
}
```

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6.3. frameworks/base/Android.mk

...

```
core/java/android/os/IPowerManager.aidl \
core/java/android/os/IOpersysService.aidl \
core/java/android/os/IRemoteCallback.aidl \
```

...

6.4. SystemServer.java

Should eventually be Context.OPERSYS_SERVICE

...

```
 try {
     Slog.i(TAG, "Opersys Service");
     ServiceManager.addService("opersys", new OpersysService(context));
} catch (Throwable e) {
     Slog.e(TAG, "Failure starting OpersysService Service", e);
}
```
...

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6.5. HelloServer.java

```java
package com.opersys.helloserver;

import android.app.Activity;
import android.os.Bundle;
import android.os.ServiceManager;
import android.os.IOpersysService;
import android.util.Log;

public class HelloServer extends Activity {
    private static final String DTAG = "HelloServer";

    /** Called when the activity is first created. */
    @Override
    public void onCreate(Bundle savedInstanceState) {
        super.onCreate(savedInstanceState);
        setContentView(R.layout.main);

        IOpersysService om =
IOpersysService.Stub.asInterface(ServiceManager.getService("opersys"));
        try {
        Log.d(DTAG, "Going to call service");
        om.setValue(20);
        Log.d(DTAG, "Service called succesfully");
        }
        catch (Exception e) {
        Log.d(DTAG, "FAILED to call service");
        e.printStackTrace();
        }
    }
}
```

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Hardware Abstraction Layer

APP

android.* → /frameworks/base/core/...

Binder

System Server → /frameworks/base/services/java/...

Foo service
JNI
"C" → /frameworks/base/services/jni/

AOSP-provided
ASL

libhardware → /hardware/libhardware/

Manuf.-provided
Manuf. license

libfoo.so → /device/[MANUF.]/[DEVICE]
/sdk/emulator/

Manuf.-provided
GPL-license

/dev/foo → Kernel or module

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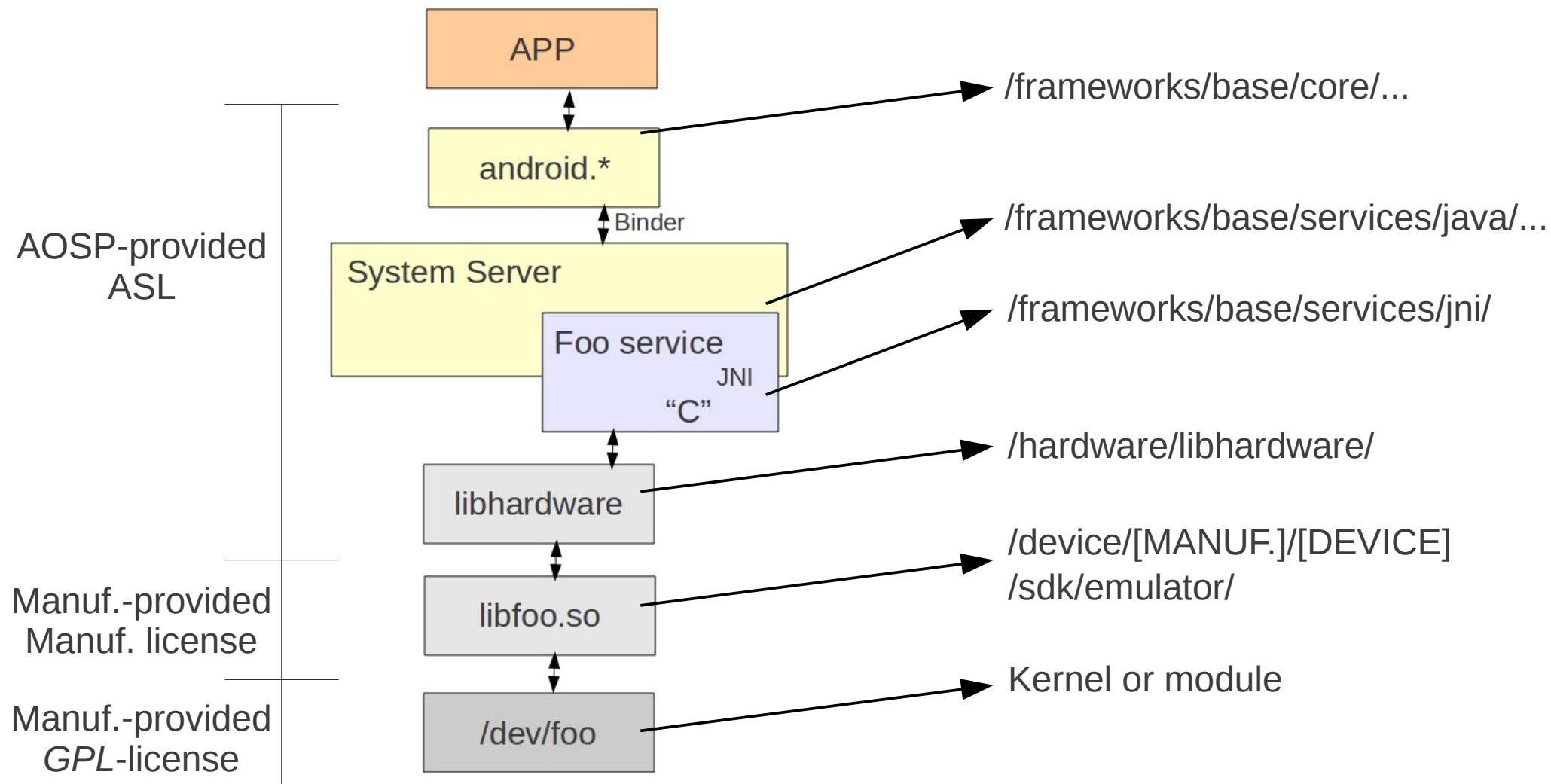
- [aosp]/hardware/libhardware/include/hardware
  - gps.h
  - lights.h
  - sensors.h
- [aosp]/hardware/ril/include/telephony/
  - ril.h
- Examples in [aosp]/device/samsung/crespo/
  - libaudio
  - libcamera
  - liblight
  - libsensors
- Using JNI to call C functions

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1. Call to JNI

```java
public class HelloJni extends Activity
{
    /** Called when the activity is first created. */
    @Override
    public void onCreate(Bundle savedInstanceState)
    {
        super.onCreate(savedInstanceState);

        /* Create a TextView and set its content.
         * the text is retrieved by calling a native
         * function.
         */
        TextView  tv = new TextView(this);
        tv.setText( stringFromJNI() + " " + pid() );
        setContentView(tv);
    }

    /* A native method that is implemented by the
     * 'hello-jni' native library, which is packaged
     * with this application.
     */
    public native String  stringFromJNI();
...
    /* this is used to load the 'hello-jni' library on application
     * startup. The library has already been unpacked into
     * /data/data/com.example.HelloJni/lib/libhello-jni.so at
     * installation time by the package manager.
     */
    static {
        System.loadLibrary("hello-jni");
    }
}
```

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2. JNI function in C

```c
jstring
Java_com_example_hellojni_HelloJni_stringFromJNI( JNIEnv* env,
                                                  jobject thiz )
{
    return (*env)->NewStringUTF(env, "Hello from JNI !");
}
```

Android Framework

- Location and components

- android.*

- Customization

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1. Location and components

- [aosp]/frameworks/base
    - /cmds   => native cmds and daemons
    - /core   => android.* and com.android.*
    - /data   => Fonts and sounds
    - /graphics   => 2D & Renderscript
    - /include   => "C" includes
    - /keystore   => security key store
    - /libs   => "C" libraries
    - /location   => Location provider
    - /media   => Stagefright, codecs, etc.
    - /native   => Native code for some frameworks components
    - /obex   => Bluetooth obex
    - /opengl   => GL library and java code
    - /packages   => A few core packages (Status Bar)
    - /services   => System server
    - /telephony => Phone related functionality
    - /tools   => A few core tools (aapt, aidl, ...)
    - /voip   => RTP & SIP interfaces
    - /vpn   => VPN functionality
    - /wifi   => Wifi manager, monitor, etc.

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2. android.*

accessibilityservice	content	hardware	pim	speech
accounts	database	inputmethodservice	preference	test
annotation	ddm	net	provider	text
app	debug	nfc	security	util
appwidget	emoji	os	server	view
bluetooth	gesture	service	webkit	widget

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3. Customization

- Extending API
- Boot screen
- Status bar
- Network
- Preloaded apps
- Browser bookmarks
- Email provider customization
- Themes

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3.1. Extending API – System service

- frameworks/base/core/java/android/

  - app/ContextImpl.java

  - content/Context.java

  - os/OpersysManager.java

3.1.1. app/ContextImpl.java

```
...
import android.os.IOpersysService;

import android.os.OpersysManager;

...
    private DownloadManager mDownloadManager = null;

    private NfcManager mNfcManager = null;

    private OpersysManager mOpersysManager = null;

...
            return getDownloadManager();
        } else if (NFC_SERVICE.equals(name)) {
            return getNfcManager();
        } else if (OPERSYS_SERVICE.equals(name)) {
            return getOpersysManager();
        }

...
```

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```
private OpersysManager getOpersysManager() {

    synchronized (mSync) {

        if (mOpersysManager == null) {

            IBinder b = ServiceManager.getService(OPERSYS_SERVICE);

            IOpersysService service = IOpersysService.Stub.asInterface(b);

            mOpersysManager = new OpersysManager(service);

        }

    }

    return mOpersysManager;

}
```

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3.1.2. content/Context.java

```
...
    /**
     * Use with {@link #getSystemService} to retrieve a
     * {@link android.nfc.NfcManager} for using NFC.
     *
     * @see #getSystemService
     */
    public static final String NFC_SERVICE = "nfc";

    /** The Opersys service **/
    public static final String OPERSYS_SERVICE = "opersys";
...
```

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3.1.3. os/OpersysManager.java

```java
package android.os;

import android.os.IOpersysService;

public class OpersysManager
{
    public void setValue(int value)
    {
        try {
            mService.setValue(value);
        } catch (RemoteException e) {
        }
    }

    public String read(int maxLength){...}

    public int write(String mString){...}

    public OpersysManager(IOpersysService service)
    {
        mService = service;
    }

    IOpersysService mService;
}
```

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3.2. Boot screen

- Create 320x480 image

- Install imagemagick

    $ sudo apt-get install imagemagick

- Convert image to .r format

    $ convert screen.jpg screen.r

- Convert image to 565 format

    $ rgb2565 < screen.r > screen.565

- Write image to flash

    $ fastboot flash splash1 screen.565

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3.3. Status bar

- Location:

  - frameworks/base/packages/SystemUI/src/com/android/systemui/statusbar

- Look for:

  - mService.setIcon(...)

- Disable icons with:

  - mService.setIconVisibility("[ICON_NAME]", false);

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3.4. Network

- Locations:
  - Global static:
    - frameworks/base/core/res/res/xml/apns.xml
  - Device static:
    - PRODUCT_COPY_FILES := vendor/acme/etc/apns-conf-us.xml:system/etc/apns-conf.xml
  - Dynamic:
    - system/etc/apns-conf.xml
- Format:

```
<apn carrier="T-Mobile US"
     mcc="310"
     mnc="260"
     apn=" wap.voicestream.com"
     user="none"
     server="*"
     password="none"
     proxy=" 216.155.165.50"
     port="8080"
     mmsc="http://216.155.174.84/servlets/mms"
/>
```

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3.5. Preloaded apps

- See build/target/products

```
PRODUCT_PACKAGES := \
    bouncycastle \
    com.android.location.provider \
    com.android.location.provider.xml \
    core \
    core-junit \
    create_test_dmtrace \
    dalvikvm \
    dexdeps \
    ...
```

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3.6. Browser bookmarks

- See packages/apps/Browser/res/values/strings.xml

```
<!-- Bookmarks -->
<string-array name="bookmarks">
    <item>Google</item>
    <item>http://www.google.com/</item>
    <item>Yahoo!</item>
    <item>http://www.yahoo.com/</item>
    <item>MSN</item>
    <item>http://www.msn.com/</item>
    <item>MySpace</item>
    <item>http://www.myspace.com/</item>
    ...
```

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3.7. Email provider customization

- See packages/apps/Email/res/xml/providers.xml

```xml
<!-- Gmail variants -->
  <provider id="gmail" label="Gmail" domain="gmail.com">
    <incoming uri="imap+ssl+://imap.gmail.com" username="$email"/>
    <outgoing uri="smtp+ssl+://smtp.gmail.com" username="$email"/>
  </provider>
  <provider id="googlemail" label="Google Mail" domain="googlemail.com">
    <incoming uri="imap+ssl+://imap.googlemail.com" username="$email"/>
    <outgoing uri="smtp+ssl+://smtp.googlemail.com" username="$email"/>
  </provider>
...
  <!-- Common US providers -->

  <provider id="aim" label="AIM" domain="aim.com">
    <incoming uri="imap://imap.aim.com" label="IMAP" username="$email"/>
    <outgoing uri="smtp://smtp.aim.com:587" username="$email"/>
  </provider>
  <provider id="aol" label="AOL" domain="aol.com">
    <incoming uri="imap://imap.aol.com" label="IMAP" username="$email"/>
    <outgoing uri="smtp://smtp.aol.com:587" username="$email"/>
  </provider>
...
```

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3.8. Themes

- See framework/base/core/res/res/values/styles.xml

Custom Toolchains and Dev Kits

- Rationale

- SDK generation

- NDK generation

- Creating a cross-dev toolchain

1. Rationale

- SDK:
  - Providing other internal teams or external developers access to your modified/custom Android APIs.
- NDK:
  - Same as SDK rationale
- Custom cross-dev toolchain:
  - To avoid having to use a binary toolchain from 3rd party.
  - To control the build parameters used to create the toolchain. Ex.: use uClibc instead of glibc.

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2. SDK generation

- Building the SDK:

  $. build/envsetup.sh

  $ lunch sdk-eng

  $ make sdk

- If API modified, do this before make:

  $ make update-api

- Location: [aosp]/out/host/linux-x86/sdk/

- Using a custom SDK:

  - Eclipse->Window->Preferences->Android->"SDK Location"

  - Eclipse->Window->"Android SDK Manager"->"Tools"

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3. NDK generation

- Build

    $ cd ndk/build/tools

    $ export ANDROID_NDK_ROOT=[aosp]/ndk

    $ ./make-release --help

    $ ./make-release

    IMPORTANT WARNING !!

    This script is used to generate an NDK release package from scratch
    for the following host platforms: linux-x86

    This process is EXTREMELY LONG and may take SEVERAL HOURS on a dual-core
    machine. If you plan to do that often, please read docs/DEVELOPMENT.TXT
    that provides instructions on how to do that more easily.

    Are you sure you want to do that [y/N]

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4. Creating a cross-dev toolchain

- **crosstool-ng**: successor to crosstool
- Available at:
    http://ymorin.is-a-geek.org/projects/crosstool
- Downloads, patches, builds, installs, etc.
- Comprises **23** steps
- Menuconfig-based
- Supports uClibc, glibc and eglibc
- Supports ARM, Blackfin, MIPS, PowerPC, SH, ...
- Fairly well maintained

- Must make sure the following are installed on Ubuntu in order to use crosstool-ng:
  - gawk
  - texinfo
  - automake
  - libtool
  - cvs
  - libncurses5-dev
- Use "sudo apt-get install" to get those

- Download and extract to ${PRJROOT}/build-tools

- Configure crosstool:

  ```
  $ cd crosstool-ng-1.10.0/

  $ ./configure
  ```

- Build and install crosstool-ng:

  ```
  $ make

  $ make install
  ```

- Configure crosstool:

  ```
  $ cd ${PRJROOT}/build-tools

  $ ct-ng menuconfig
  ```

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- Options:
  - Paths->Prefix directory: ${PREFIX}/${CT_TARGET}
  - Target options->architecture: powerpc
  - OS->Target OS: linux
  - C library->C library: glibc
  - C library->Extra flags: -U_FORTIFY_SOURCE
  - Debug facilities: gdb & strace
- Build the toolchain:

```
$ ct-ng build
```

Compatibility Test Suite

- Android Compatibility Program:
  - Source code to Android stack
  - Compatibility Definition Document (CDD) – Policy
  - Compatibility Test Suite (CTS) – Mechanism
- Each Android version has own CDD & CTS
- CTS:
  - Part of AOSP
  - Run from host using USB over to attached device
  - Based on JUnit
  - Runs various test apps on target
  - Relies on ADB
  - Provides report to be be analyzed and/or sent back to Google

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On your machine

Download and install the CTS.

Run the CTS.

Store and view results.

Devices you attach to your machine

Test execution

Test results

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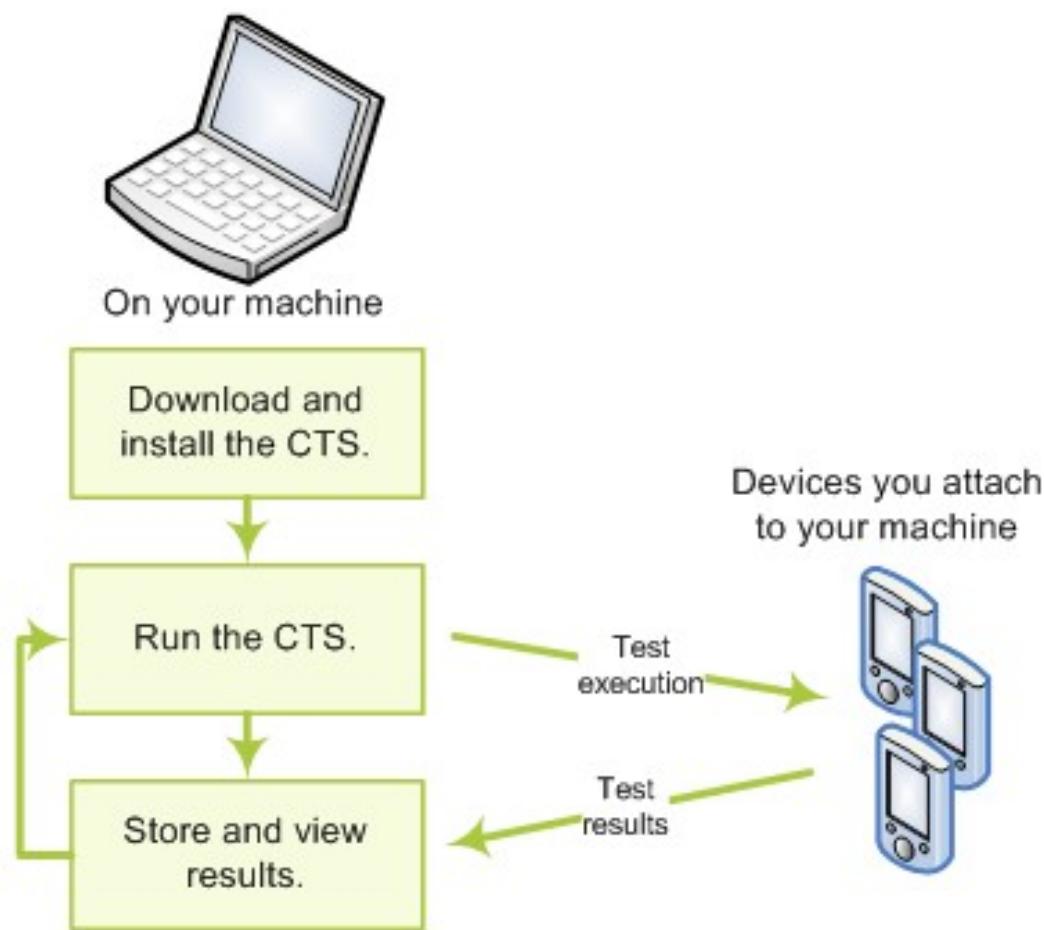
- Report:
  - .zip file containing XML files and screen-shots
  - Sent to: cts@android.com
- Building the CTS:

  $. build/envsetup.sh

  $ make cts
- Launching the CTS:

  $ cd out/host/linux-x86/bin/

  $ ./cts

  $ cts_host >

  $ cts_host > help

  ...

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- Using the CTS:

  $ cts_host > ls --plan
  List of plans (8 in total):
  Signature
  RefApp
  VM
  Performance
  AppSecurity
  Android
  Java
  CTS

  $ ./cts start --plan CTS

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- Areas covered:
  - Signature tests
  - Platform API tests
  - Dalvik VM tests
  - Platform Data Model
  - Platform Intents
  - Platform Permissions
  - Platform Resources

Hacks, Variants, Tricks, and Resources

1. AOSP's limitations
2. Tearing AOSP apart
3. Forks
4. Ports
5. Mods
6. Melds

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1. AOSP's limits

- Rigid

- Closed dev model

- Fits Google's prerogatives

- Excludes a lot of stuff

- ... IOW, doesn't always fit what you need

2. Tearing AOSP apart

- Forks

- Ports

- Mods

- Melds

2.1. Forks

- Cyanogenmod
- Replicant
- MIUI

2.2. Cyanogenmod

- After-market handset firmware

- Requires rooted phone

- http://www.cyanogenmod.com

- Advertized features:

  - Lockscreen Gestures

  - Phone Goggles

  - OpenVPN

  - Incognito mode

  - Themes support

  - DSP Equalizer

- More interestingly:
  - http://wiki.cyanogenmod.com/
  - https://github.com/CyanogenMod
  - Includes Busybox
  - Custom Launcher (ADWLauncher)
  - Lots of tiny tweaks and mods ... worth doing a "diff"

2.3. Replicant

- Android distro that is 100% Free Software
- http://replicant.us/
- Includes FDroid free software app store
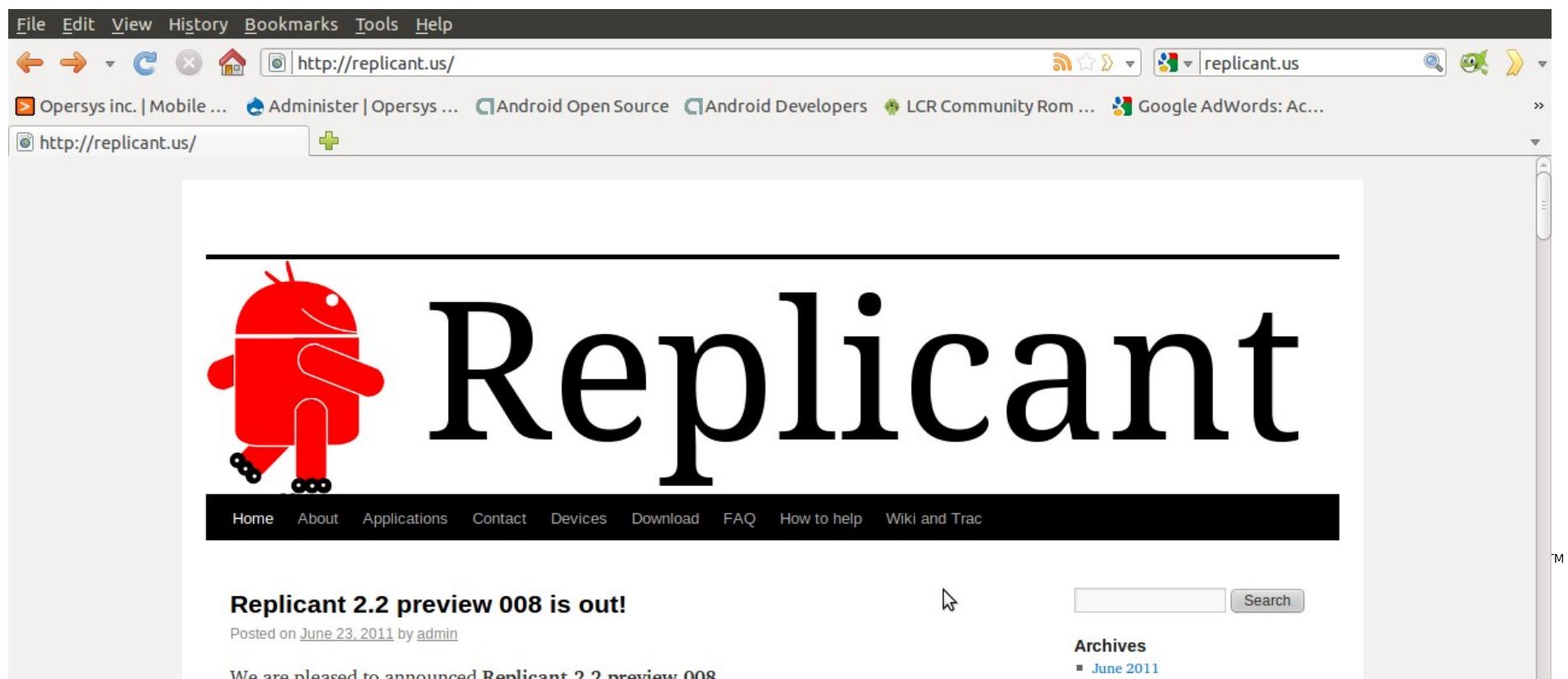
2.4. MIUI

- Closed-source fork with slick UI enhancements

- Many translations

- http://en.miui.com/

- Advertized features:

    - Home screen

    - Dialer

    - SMS

    - Contacts

    - Themes

    - Camera

    - Gallery

   - Net disk, File manager, Traffic monitor, Backup, Notes, ...

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3. Ports

- RIM Playbook

- BlueStacks

- Alien Dalvik

3.1. RIM Playbook

3.2. BlueStacks

3.3. Alien Dalvik (Myriad Group)

Myriad Alien Dalvik on Meego

Myriad Alien Dalvik will be first commercially available on the MeeGo platform. A very tight integration to both the Android SDK and the MeeGo SDK (QTCreator) makes it very easy to modify, package and test applications.

Most Android applications can run unmodified as the vast majority of Android APIs are supported and tight integration with the QT framework leads to a seamless user experience.

Ported applications demonstrate no loss of performance compared to the Android applications running in the native environment, thanks to Myriad Dalvik Turbo technology. As an example, when running on the Nokia N900, Myriad Alien Dalvik demonstrates similar or superior performances.

First implemented on the Meego/Maemo platform, Myriad Alien Dalvik can support other platforms, to be developed depending on customers needs.

Figure 2 : Alien Dalvik running Android Photoshop on Nokia N900 vs native application on HTC legend

Myriad Alien Dalvik runs the Photoshop Android application on a Nokia N900. The application shows exactly as the original application running on an HTC legend. While the mobile handsets are very similar - both using 600MHz ARM processors, performance appear the same or better on the Nokia thanks to the use of Myriad Dalvik Turbo technology.

4. Mods

- XDA Developers

- ...

5. Melds

- Stock glibc stack (as covered earlier)
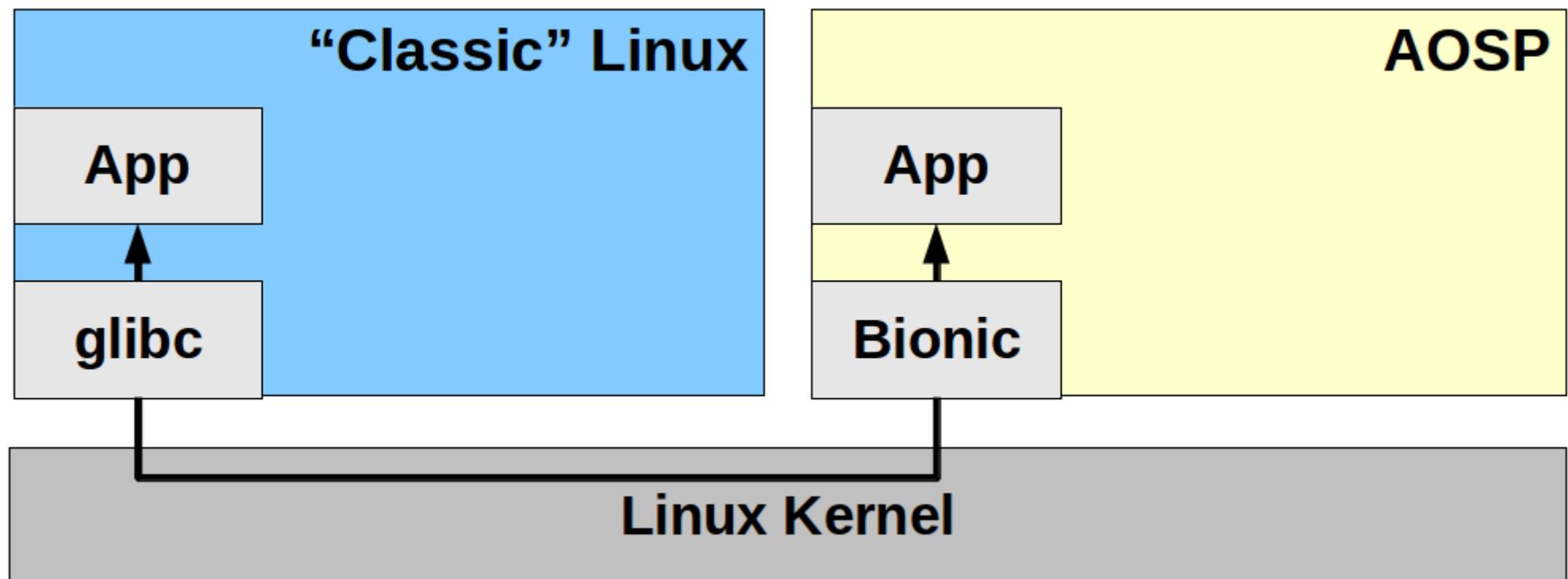
- Custom stacks

Manipulating storage devices

1. MTD subsystem concepts

2. MTD usage basics

3. Native CFI flash

4. Disk devices

5. Swapping

1. MTD subsystem concepts

- MTD support for solid-state storage devices: flash, DOC, ROM, RAM, etc.

- 3 layers:

  - MTD chip drivers

  - MTD "glue logic"

  - MTD "user modules"

- Main MTD project URL:

  http://www.linux-mtd.infradead.org

- Chip drivers:
  - NAND
  - OneNAND
  - CFI
  - NOR
  - RAM, ROM, and absent chips
  - Uncached RAM
  - Virtual devices for testing and evaluation
  - DiskOnChip (bit rot)

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- "Mapping drivers" allow the MTD subsystem to locate and access the actual chips.

- When your chip is supported, you need to write the mapping driver for your board.

- MTD can manage multiple instances of a chip

- MTD can partition and concatenate devices

- User-modules provide additional functionality which allow chips to be accessed through the kernel's virtual filesystem layer.

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- User-modules:
  - UBIFS:
    - Works on top of UBI (Unsorted Block Images), on top of MTD
    - UBI provides wear-leveling
    - Scalability
    - Fast mount, fast I/O, on-the-flight compression
    - Provides power-down reliability
  - YAFFS2
    - NAND flash
    - Includes wear-leveling
    - No compression
    - Provides power-down reliability (no fsck)

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- JFFS2 (Journalling Flash File System version 2):
    - Implements log-structured FS on device
    - FS recreated in RAM at mount time
    - Includes wear-leveling
    - Implements data compression
    - Provides power-down reliability (no fsck)
- NFTL (NAND Flash Translation Layer) and INFTL (Inverse NFTL) for M-Systems DiskOnChip devices
- FTL (Flash Translation Layer), part of PCMCIA std.

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- Char device:
  - Provides direct access to chip as a char device
  - Very useful for programming device in Linux
- Caching block device:
  - Provides a simple block device interface to MTD devices
  - Can mount a block FS straight on it for reading & writing
  - Does NOT provide power-down reliability
  - Does NOT implement smart device management
- Read-only block device:
  - Same as caching block device, but read-only

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2. MTD usage basics

- MTD subsystem developed independently from kernel.

- Recommended to use latest kernel

- Bleeding edge is in MTD git repo

- MTD subsystem requires /dev entries that differ from devices.txt file specification.

- MTD /dev entries are as listed in BELS table 7.1 and 7.2.

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- Types of MTD /dev entries:
    - mtdN => each instance is separate MTD device or partition.
    - mtdrN => each instance is read-only copy of mtdN entry.
    - mtdblockN => each instance is block device copy of mtdN.
    - nftlN => each instance is separate NFTL device. Further numbered like hd.
    - ftlN => similar naming as nftlN
- If MTD devices are accessible on host, can use the packaged device creation script.

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- Main MTD kernel configuration options:
  - Memory Technology Device (MTD) support:
    - Must be set to use MTD subsystem
  - MTD partitioning/concatenating support:
    - Enables partitioning/concatenating MTD devices
  - Direct char device access to MTD devices:
    - Required for accessing MTD devices as char devices
  - Caching block device access to MTD devices:
    - Enables mounting MTD device as normal rw block device
  - Read-only block device access to MTD devices:
    - Same as above, but read-only
  - FTL (Flash Translation Layer)
    - Provides FTL MTD user module
  - NFTL (NAND Flash Translation Layer)
    - Provides NFTL MTD user module

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- INFTL (Inverse NAND Flash Translation Layer)
  - Provides INFTL MTD user module
- Can only set mtdblock or mtdblock_ro as built-in. Can set both as modules.
- Support for JFFS2 and JFFS is found in the "File Systems" submenu.
- MTD Submenus:
  - RAM/ROM/Flash chip drivers:
    - Support for CFI, JEDEC, non-CFI, RAM, ROM, etc.
  - Mapping drivers for chip access
    - Default mapping drivers for quite a few boards
  - Self-contained MTD device drivers
    - Uncached RAM, VM test drv, blk dev emu, DOC devices

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- NAND Flash Device Drivers
  NAND flash
- During development:
  - Build MTD options as modules
- For production:
  - Select MTD options as built-in
- MTD utilities:
  - MTD subsystem requires special tools (can't use conventional disk utilities.)
  - MTD utilities are very powerful. Be careful when using them, you could destroy your device.

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- Generic tools:
  - flash_info   =>   get erase information
  - flash_erase   =>   erase device
  - flash_eraseall =>   erase entire device
  - flash_unlock =>   unlock flash protection
  - flash_lock   =>   lock flash protection
  - flashcp   =>   copy file to flash
  - doc_loadbios =>   copy bootloader to device
  - mtd_debug   =>   access MTD debugging

- **Filesystem creation tools:**
  - mkfs.jffs2 => create JFFS2 filesystem image
  - mkfs.jffs => create JFFS filesystem image
  - jffs2dump => dumps the content of a JFFS2 image (can't mount JFFS2 on loopback.)
- **NFTL tools:**
  - nftl_format => write NFTL format on device
  - nftldump => dump NFTL content to file
- **FTL tools:**
  - ftl_format => write FTL format on device
  - ftl_check => verify FTL format

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- NAND chip tools
  - nandwrite   =>   write to NAND device
  - nandtest   =>   test NAND device
  - nandump   =>   dump NAND device content
- Installing MTD tools on host:
  - Get and put in ${PRJROOT}/build-tools:
    - Zlib: http://www.zlib.net
    - LZO: http://www.oberhumer.com/opensource/lzo/
    - Libacl:http://oss.sgi.com/projects/xfs/
    - MTD: git://git.infradead.org/mtd-utils
  - Make sure you have LZO And UUID installed:
    ```
    $ sudo apt-get install liblzo2-dev
    $ sudo apt-get install uuid-dev
    ```

- Installing MTD tools for target:
  - Configure and compile zlib:
    ```
    $ cd ${PRJROOT}/build-tools/
    $ tar xvzf zlib-1.2.5.tar.gz
    $ zlib-1.2.5
    $ CC=${TARGET}-gcc \
    > LDSHARED="${TARGET}-ld -shared" \
    > ./configure --shared
    $ make
    $ make prefix=${TARGET_PREFIX} install
    ```
  - Configure and compile lzo:
    ```
    $ cd ${PRJROOT}/build-tools/
    $ tar xvzf lzo-2.03.tar.gz
    $ cd lzo-2.03
    $ CC=powerpc-unknown-linux-gnu-gcc ./configure \
    > --enable-shared --host=i686-linux  \
    > --target=powerpc-unknown-linux-gnu
    $ make
    $ make prefix=${TARGET_PREFIX} install
    ```

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- Got to ${PRJROOT}/build-tools

- Extract git snapshot:

```
$ git clone git://git.infradead.org/mtd-utils
```

- Copy the acl.h header:

```
$ cd ${PRJROOT}/build-tools
$ tar xvzf acl_2.2.47-1.tar.gz
$ mkdir ${PRJROOT}/mtd-utils/include/sys
$ acl-2.2.47/include/acl.h \
> ${PRJROOT}/mtd-utils/include/sys
```

- Go to mtd-utils/ and build tools:

```
$ make
```

- Install tools:

```
$ make DESTDIR=${PREFIX} SBINDIR="" install
```

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3. Native CFI flash

- Relatively straight-forward
- Kernel configuration:
  - Memory Technology Device (MTD) support
  - MTD partitioning/contactenating support, if needed
  - Direct char access to MTD devices
  - Caching block device access to MTD devices
  - "RAM/ROM/..." submenu: Detect flash chip by Common Flash Interface (CFI) and Support for Intel/Sharp and AMD/Fujitsu flash chips.
  - "Mapping drivers ..." submenu: select CFI mapping for board

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- Partitioning can be done in mapping driver
- Newer partitioning method using boot param:

```
mtdparts=0:256k(ppcboot)ro,768k(kernel),1m(user),-(initrd);
    1:2m(cramfs),-(jffs2)
```

- For TQM860L, partition is as follows:

```
TQM flash bank 0: Using static image partition definition
Creating 4 MTD partitions on "TQM8xxL Bank 0":
0x00000000-0x00040000 : "ppcboot"
0x00040000-0x00100000 : "kernel"
0x00100000-0x00200000 : "user"
0x00200000-0x00400000 : "initrd"
TQM flash bank 1: Using static file system partition definition
Creating 2 MTD partitions on "TQM8xxL Bank 1":
0x00000000-0x00200000 : "cramfs"
0x00200000-0x00400000 : "jffs2"
```

- Partitions are on erase block boundaries (128KB)

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- Creation of necessary /dev entries:

```
$ cd ${PRJROOT}/rootfs/dev
$ su -m
Password:
# for i in $(seq 0 5)
> do
> mknod mtd$i c 90 $(expr $i + $i)
> mknod mtdblock$i b 31 $i
> done
# exit
$ ls -al mtd*
crw-rw-r-- 1 root root 90, 0 Jun 25 17:19 mtd0
crw-rw-r-- 1 root root 90, 2 Jun 25 17:20 mtd1
crw-rw-r-- 1 root root 90, 4 Jun 25 17:20 mtd2
crw-rw-r-- 1 root root 90, 6 Jun 25 17:20 mtd3
crw-rw-r-- 1 root root 90, 8 Jun 25 17:20 mtd4
crw-rw-r-- 1 root root 90,10 Jun 25 17:20 mtd5
brw-rw-r-- 1 root root 31, 0 Jun 25 17:17 mtdblock0
brw-rw-r-- 1 root root 31, 1 Jun 25 17:17 mtdblock1
brw-rw-r-- 1 root root 31, 2 Jun 25 17:17 mtdblock2
...
```

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- Must erase flash before writing:

```
# flash_eraseall /dev/mtd3
Erased 2048 Kibyte @ 0 -- 100% complete.
```

- Writing:

```
# cat /tmp/initrd.bin > /dev/mtd3
```

- Reading:

```
# dd if=/dev/mtd0 of=/tmp/u-boot.img
```

4. Disk devices

- There is a lot of documentation on how to manipulate disk devices in Linux.
- Main tool: `fdisk`

```
# fdisk
Command (m for help): m
Command action
   a   toggle a bootable flag
   b   edit bsd disklabel
   c   toggle the dos compatibility flag
   d   delete a partition
   l   list known partition types
   m   print this menu
   n   add a new partition
   o   create a new empty DOS partition table
   p   print the partition table
   q   quit without saving changes
   s   create a new empty Sun disklabel
   t   change a partition's system id
   u   change display/entry units
   v   verify the partition table
   w   write table to disk and exit
   x   extra functionality (experts only)
```

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- Once partitions are created, use the `mkfs` utility described earlier to create a filesystem type on the device and use `mount` to mount new filesystem.

- If need be, use LILO as described earlier to install bootloader on secondary hard-disk.

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5. Swapping

- Discouraged for all types of embedded Linux systems, except large ones.

- Strongly discourage for any system relying on solid-state storage.

- Use `swapon` to enable swapping on a device and `swappoff` to disable swapping on a device.

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Choosing and installing the rootfs

1. Selecting a filesystem
2. Writing images to flash using NFS
3. CRAMFS
4. ROMFS
5. Squashfs
6. UBIFS
7. JFFS2
8. Disk filesystem over RAM disk
9. Comparing filesystem image size
10. TMPFS
11. Live updates

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1. Selecting a filesystem

- Important part of system design

- Requires understanding of filesystem capabilities and system's dynamics.

- Filesystem characteristics:

  - Write

  - Persistent

  - Power down reliability

  - Compression

  - Lives in RAM

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- **Selecting a filesystem:**
  - **RAM disk:**
    - Large amount of RAM
    - Limited amount of flash
    - Don't need to keep changes across reboots
    - For persistence, use with additional filesystem
    - Easiest way to get self-hosting target
    - Replaced by initramfs
  - **CRAMFS**
    - Compressed ROM filesystem
    - Requires less RAM than a RAM disk
    - Cannot be written to (read-only)

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- Maximum file-size of 16 MB
- No current or parent directories
- 16-bit UID / 8-bit GID
- All timestamps set to Epoch
- All files have link count of 1
- Requires block device

- ROMFS
  - ... read-only
  - Requires block device
  - Stores the bare-minimum details required for a filesystem
  - Does not store: dates, permissions
  - Used to be used by uClinux since no protection anyway
  - No compression

- Squashfs:
  - Compressed ROM filesystem, better than CRAMFS
  - Requires block device
- UBIFS:
  - JFFS2-replacement
  - All benefits of JFFS2 w/ better performance and scalability
  - Benefits most apparent on large images
- JFFS2
  - Compressed
  - Read / write
  - Perfect for devices that need field-updating
  - Power-down reliability (no roll-back)
  - Wear-leveling

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- Using a regular disk device:
  - Have a look at the slew of disk filesystems supported by Linux. BELS contains a few pointers if you're out of inspiration.

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2. Writing images to flash using NFS

- May not have access to flash device from host, but may need to put image generated on host in target flash.
- Steps:
  1. Generate image on host
  2. Cross-build MTD utilities for target and install in ${PRJROOT}/rootfs
  3. Mount target's rootfs using NFS
  4. On host, copy image to directory mounted by target as rootfs.
  5. Use MTD utilities to copy image from rootfs to appropriate /dev entry.

3. CRAMFS

- Latest available from: http://sourceforge.net/projects/cramfs/

- Download CRAMFS (1.1) utilities into your ${PRJROOT}/build-tools directory and uncompress there.

- Build and install CRAMFS utilities:

```
$ cd ${PRJROOT}/build-tools/cramfs-1.1
$ make
$ cp cramfsck mkcramfs ${PREFIX}/bin/
```

- Creating a rootfs image:

```
$ cd ${PRJROOT}
$ mkcramfs rootfs/ images/cramfs.img
Directory data: 3960 bytes
Everything: 3452 kilobytes
Super block: 76 bytes
CRC: f74fb18c
warning: gids truncated to 8 bits (this may be a security concern)
```

- Example filesystem image writing to device, if MTD device accessible on host:

```
$ su -m
Password:
# cat images/cramfs.img > /dev/mtd5
# exit
```

- Use NFS-writing if device not accessible from host

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4. ROMFS

- Latest available from: http://romfs.sourceforge.net/
- Download genromfs (0.5.2) utilities into your ${PRJROOT}/build-tools directory and uncompress there.
- Build and install genromfs utilities:

```
$ cd ${PRJROOT}/build-tools/genromfs-0.5.2
$ make
$ cp genromfs ${PREFIX}/bin
```

- Creating a ROMFS image:

```
$ cd ${PRJROOT}
$ su -m
# genromfs -d rootfs/ -f images/romfs.img
# chown karim:karim images/romfs.img
```

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5. Squashfs

- Latest available from: http://www.squashfs.org
- Download squashfs (4.1) into your ${PRJROOT}/build-tools directory and uncompress there.
- Make sure you have libacl1-dev installed:
  ```
  $ sudo apt-get install libacl1-dev
  ```
- Build and install genromfs utilities:
  ```
  $ cd ${PRJROOT}/build-tools/squashfs4.1
  $ make
  $ cp mksquashfs unsquashfs ${PREFIX}/bin
  ```
- Creating a SquashFS image:
  ```
  $ cd ${PRJROOT}
  $ mksquashfs rootfs/ images/squashfs.img
  ```

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6. UBIFS

- Tools already installed as part of MTD utilities
- Creating a UBIFS image:

```
$ cd ${PRJROOT}
$ mkfs.ubifs -m 512 -e 128KiB -c 100 -x zlib \
> -r rootfs images/ubifs.img
```

7. JFFS2

- Tools already installed as part of MTD utilities.

- Creating a JFFS2 image:

  ```
  $ cd ${PRJROOT}
  $ mkfs.jffs2 -r rootfs/ -o images/jffs2.img
  ```

- Can't mount on loopback

- May use `jffs2dump`

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8. Disk filesystem over RAM disk

- RAM disks behave like block devices

- The RAM disk driver can manage multiple RAM disk instances.

- initrd is mechanism to provide kernel with initial RAM disk for use as rootfs at startup.

- Creating blank filesystem image:

```
$ cd ${PRJROOT}
$ mkdir tmp/initrd
$ dd if=/dev/zero of=images/initrd.img bs=1k count=8192
8192+0 records in
8192+0 records out
8388608 bytes (8.4 MB) copied, 0.0425007 s, 197 MB/s
```

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- Formating filesystem image and mounting it:

```
$ su -m
Password:
# /sbin/mke2fs -F -v -m0 images/initrd.img
mke2fs 1.41.12 (17-May-2010)
fs_types for mke2fs.conf resolution: 'ext2', 'small'
Calling BLKDISCARD from 0 to 8388608 failed.
Filesystem label=
OS type: Linux
Block size=1024 (log=0)
Fragment size=1024 (log=0)
Stride=0 blocks, Stripe width=0 blocks
2048 inodes, 8192 blocks
0 blocks (0.00%) reserved for the super user
First data block=1
Maximum filesystem blocks=8388608
1 block group
8192 blocks per group, 8192 fragments per group
2048 inodes per group
...

# mount -o loop images/initrd.img tmp/initrd
```

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- Copying rootfs, umounting, and compressing:

```
# cp -av rootfs/* tmp/initrd
`rootfs/bin' -> `tmp/initrd/bin'
`rootfs/bin/busybox' -> `tmp/initrd/bin/busybox'
`rootfs/bin/ash' -> `tmp/initrd/bin/ash'
`rootfs/bin/cat' -> `tmp/initrd/bin/cat'
`rootfs/bin/chgrp' -> `tmp/initrd/bin/chgrp'
`rootfs/bin/chmod' -> `tmp/initrd/bin/chmod'
...
# umount tmp/initrd
# exit
$ gzip -9 < images/initrd.img > images/initrd.bin
```

- The initrd mechanism is largely favored to be replaced by initramfs.

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9. Disk filesystem over initramfs

- Initramfs used by kernel at boot time

- Can be linked directly into kernel image

- Creating an initramfs image:

```
$ cd ${PRJROOT}/rootfs
$ find . | cpio -o -H newc | gzip > ../images/initramfs.img
```

10. Comparing filesystem image sizes

- Let's take a look at what we've generate so far:

```
$ cd ${PRJROOT}/images
$ ls -al \
> cramfs.img romfs.img squashfs.img ubifs.img jffs2.img init*
-rw-r--r-- 1 stage stage 3719168 2011-02-25 14:49 cramfs.img
-rw-r--r-- 1 stage stage 3492683 2011-02-25 11:28 initramfs.img
-rw-r--r-- 1 stage stage 8388608 2011-02-25 15:19 initrd.img
-rw-r--r-- 1 stage stage 4237296 2011-02-25 15:13 jffs2.img
-rw-r--r-- 1 stage stage 6949888 2011-02-25 14:50 romfs.img
-rw-r--r-- 1 stage stage 3264512 2011-02-25 14:58 squashfs.img
-rw-r--r-- 1 stage stage 5898240 2011-02-25 15:13 ubifs.img
```

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11. Mounting directories on TMPFS

- Dynamically resizeable RAM-based FS

- Perfect for holding transient data

- No need to create beforehand or format

- Mount:

```
# mount -t tmpfs none /tmp -o size=4m
```

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12. Live updates

- Only RAM disks can be replaced in its entirety while mounted.
- CRAMFS, ROMFS, Squashfs cannot be replaced
- All rootfses based on other filesystems must be updated while mounted by modifying files and directories one-by-one.
- Four main ways:
  - `rsync`
  - Package management tools
  - `netflash`
  - Ad hoc scripts

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- The `rsync` utility:
  - Replaces Unix's `rcp`
  - Allows network update
  - Can be used over SSH
  - Available from: http://samba.anu.edu.au/rsync/
  - Need to have daemon running on host and client running in the embedded system.
  - `rsync` most likely already installed by distro.
  - Download (2.5.6) and extract package in your ${PRJROOT}/sysapps directory.

- Configure compile and install `rsync`:

```
$ cd ${PRJROOT}/sysapps/rsync-2.5.6/
$ CC=powerpc-linux-gcc \
> CPPFLAGS="-DHAVE_GETTIMEOFDAY_TZ=1" ./configure \
> --host=$TARGET --prefix=${TARGET_PREFIX}
$ make
$ cp rsync ${PRJROOT}/rootfs/bin
$ powerpc-linux-strip ${PRJROOT}/rootfs/bin/rsync
```

- Use on target:

```
# rsync -e "ssh -l root" -r -l -p -t -D -v \
> --progress \
> 192.168.172.100:/home/karim/example-sys/rootfs/* /
```

- To do a dry run, add "-n" parameter

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- Package management tools:
  - dpkg
  - RPM
  - BusyBox dpkg
- The `netflash` utility:
  - Part of uClinux-dist

Kernel internals

1. Brief history
2. Features
3. General architecture
4. Source layout
5. Process management
6. Filesystems
7. Memory management
8. Communication facilities and interfacing
9. Loadable modules

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10. Interrupt and exception management

11. Timing

12. Locking primitives

13. Kernel startup

14. Dealing with kernel failure

1. Brief history

- Started on Minix by Linus Torvalds (who wanted to call is Freax ...)
- Rechristened "Linux" by FTP site admin
- Once public, users and contributions grew at a very rapid rate.
- Closed the GNU project's loop
- Most important events:
  - 17 September 1991: Version 0.01
  - 3 December 1991: Version 0.10
  - 8 March 1992: Version 0.95

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- 13 December 1992: Version 0.99
- 13 March 1994: Version 1.0
- 7 March 1995: Version 1.2.0
- 9 July 1996: Version 2.0
- 26 January 1999: Version 2.2.0
- 4 January 2001 : Version 2.4.0
- 17 December 2003: Version 2.6.0
- 21 July 2011: Version 3.0.0

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2. Features

- Portable / Architecture-independent
- Scalable
- Monolithic
- Dynamically extensible (modules)
- Multi-user environment
- Multi-process / Multi-threading
- Memory protection
- Preemptable (starting in 2.5.x) ... but not real-time
- Symmetric multi-processor

- Slew of filesystems

- Slew of networking protocols / NICs

- Quite a few executable formats

- ...

3. General architecture

Applications

↓ System calls   ↑ Signals

Kernel

Process Management	Kernel Management	Memory Management	Communication Management	Virtual Filesystem

Hardware-specific Management	Protocols	FS
	NIC drivers	Block	Char

↑ Interrupts / Traps / Exceptions

CPU	Basic Hardware	Main Memory	NIC	HD	?

4. Source layout

Applications

arch/ARCH/kernel/entry.S   kernel/signal.c

Kernel

kernel/*
sched.c,
fork.c, exit.c

kernel/*
capability.c,
sys.c,
softirq.c,
panic.c, ...

mm/*
arch/ARCH/mm/
kernel/*

fs/pipe.c,
fs/fifo.c,
ipc/*, net/*

fs/*

arch/ARCH/*

net/*

drivers/net/*

fs/*/*

drivers/block/*

drivers/char/*

arch/ARCH/kernel: irq.c, traps.c

| CPU | Basic Hardware | Main Memory | NIC | HD | ? |

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arch	112MB	=>	architecture-dependent functionality
block	600KB	=>	block layer
Documentation	17MB	=>	main kernel documentation
drivers	231MB	=>	all drivers
fs	31MB	=>	virtual filesystem and all fs types
include	20MB	=>	complete kernel headers
init	150KB	=>	kernel startup code
ipc	224KB	=>	System V IPC
kernel	**4.7MB**	**=>**	**core kernel code**
mm	2.2MB	=>	memory management
net	20MB	=>	networking core and protocols
scripts	1.1MB	=>	scripts used to build kernel
tools	2.1MB	=>	misc. kernel-related tools

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- ## arch/

2.4M	alpha
29M	arm
1.4M	avr32
5.3M	blackfin
4.9M	cris
1.4M	frv
856K	h8300
4.6M	ia64
8.0K	Kconfig
1.4M	m32r
5.7M	m68k
1.1M	m68knommu
1.2M	microblaze

11M	mips
1.7M	mn10300
2.4M	parisc
13M	powerpc
2.4M	s390
636K	score
5.4M	sh
4.7M	sparc
1.9M	tile
1.9M	um
8.5M	x86
1.4M	xtensa

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- arch/powerpc:

  2.0M boot
  548K configs
  2.0M include
  2.1M kernel
  384K kvm
  216K lib
  204K math-emu
  472K mm
  156K oprofile
  3.4M platforms
  848K sysdev
  392K xmon

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- ## drivers/

accessibility	cpufreq	hwmon	mca	parisc	sbus	uio
acpi	cpuidle	i2c	md	parport	scsi	usb
amba	crypto	ide	media	pci	serial	uwb
ata	dca	idle	memstick	pcmcia	sfi	vhost
atm	dio	ieee802154	message	platform	sh	video
auxdisplay	dma	infiniband	mfd	pnp	sn	virtio
base	edac	input	misc	power	spi	vlynq
block	eisa	isdn	mmc	pps	ssb	w1
bluetooth	firewire	Kconfig	mtd	ps3	staging	watchdog
cdrom	firmware	leds	net	rapidio	tc	xen
char	gpio	lguest	nubus	regulator	telephony	zorro
clocksource	gpu	macintosh	of	rtc	thermal	
connector	hid	Makefile	oprofile	s390	tty	

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- **include/**

```
acpi            config  drm     keys    math-emu  mtd  pcmcia  rxrpc  sound  video

asm-generic  crypto  Kbuild  linux  media     net  rdma    scsi   trace  xen
```

- Looking for something:
  - Try `grep`
  - Have a look at the Linux Cross-Referencing project:
    - URL: http://lxr.linux.no/
    - Code: http://lxr.sourceforge.net/
  - Advanced kernel searching/understanding:
    - CScope: http://cscope.sourceforge.net/
    - KScope front-end: http://kscope.sourceforge.net/
  - ETAGS (emacs)

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5. Process management

- Process descriptor (include/linux/sched.h: task_struct):

Process state	=>	*state*
Identification	=>	*pid*, t*gid*
Relationship	=>	**parent*, children*
Scheduling	=>	*time_slice*, sched_class, *rt_priority, prio, static_prio*
Files	=>	**files*
Memory	=>	**mm*

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- Main process list:
  - Doubly-linked list
  - List head: *init_task*
- Currently running process (macro): *current*
- Task creation:

    kernel/fork.c:*do_fork()*

- Threads:

    arch/ARCH/kernel/process.c:*sys_clone()*

- *sys_clone()* ends up calling *do_fork()*

- **Scheduling:**
  - **Process states:** TASK_RUNNING, TASK_INTERRUPTIBLE, TASK_UNINTERRUPTIBLE, TASK_STOPPED, TASK_TRACED, EXIT_ZOMBIE, ...
  - **Main scheduling function:**

    kernel/sched.c: *schedule()*
  - **Scheduling policies:**
    - SCHED_NORMAL
      - Main scheduling policy for Linux processes
    - SCHED_FIFO:
      - Process has CPU until it gives it up or no other higher priority task comes along.
    - SCHED_RR:
      - CPU is shared between "real-time" tasks
    - ...

- **Address space:**
  - include/linux/mm_types.h:*mm_struct*
  - Fields: *mmap, mm_count, start_code, end_code, start_data, end_data, start_brk, brk, start_stack, arg_start, arg_end, env_start, env_end*

- **Special tasks:**
  - init => first process on system
  - ksoftirqd/0 => soft-irq thread for avoiding process starvation
  - events/0 => kernel's work queue handler (was keventd)
  - khubd => USB hub thread
  - kswapd0 => pageout daemon

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6. Filesystems

- ## Virtual filesystem: fs/*

attr.c	=>	file attributes
block_dev.c	=>	block device access
buffer.c	=>	buffer cache
char_dev.c	=>	char device access
dcache.c	=>	dentry (directory entry) cache
notify/	=>	directory change notifications
quot/	=>	disk quota
exec.c	=>	*exec()* and its variants
fcntl.c	=>	*fcntl()*
fifo.c	=>	FIFO handling
file.c	=>	manage process' fd array
file_table.c	=>	file table manipulation
inode.c	=>	inode handling
ioctl.c	=>	*ioctl()*
locks.c	=>	file locking

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```
namei.c          =>          pathname lookup
namespace.c      =>          filesystem mounting
open.c           =>          open()
pipe.c           =>          pipe management
readdir.c        =>          directory reading
read_write.c     =>          read() and write(), and variants
select.c         =>          select() and poll()
stat.c           =>          stat()
super.c          =>          filesystem type management
```

- **Root filesystem mounting: init/do_mounts.c**

  prepare_namespace()

- **RAM disk handling (within init/):**
  - do_mounts_initrd.c: initrd_load()
  - do_mounts_rd.c: *rd_load_image(), identify_ramdisk_image()*
  - do_mounts_initrd.c: *handle_initrd(),*

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7. Memory management

- Arch-independent portion: mm/*

bootmem.c	=>	boot memory allocation / handling
filemap.c	=>	handling for *mmap()*'ed files
highmem.c	=>	RAM above 896MB / up to 64 GB
memory.c	=>	page and page table manipulation
mlock.c	=>	memory region locking
mmap.c	=>	*mmap()*
mprotect.c	=>	memory protection mechanisms
mremap.c	=>	*mremap()*
nommu.c (2.5)	=>	*functions for MMU-less processors*
oom_kill.c	=>	process killing when short on memory
page_alloc.c	=>	page allocation / freeing
page_io.c	=>	reading / writing swap pages
shmem.c	=>	shared memory management
slab.c	=>	memory allocation for kernel
swap.c	=>	swap default

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```
swapfile.c      =>      swap space management
swap_state.c    =>      swap page caching
vmalloc.c       =>      memory region allocation
vmscan.c        =>      page out daemon
```

- ## Architecture-dependent portion: arch/ARCH/mm/*

```
fault.c       all  =>      page fault handler
init.c        all  =>      memory initialization
ioremap.c     x86=>      remapping of I/O range to kernel space
pageattr.c    x86=>      page attributes handling
pgtable.c     ppc=>      page table manipulation
ppc_mmu.c     ppc=>      MMU handling for PPC
tlb.c         ppc=>      TLB flushing
```

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8. Communication facilities and interfacing

- Signals   =>   kernel/signal.c
- Pipes   =>   fs/pipe.c
- FIFOs   =>   fs/fifo.c
- Sockets   =>   net/socket.c
- System V IPC =>   ipc/ : msg.c, sem.c, shm.c
- System calls   =>   arch/ARCH/kernel/entry.S
- Adding new system calls:
    1. Add entry to arch/ARCH/kernel/entry.S
    2. Add entry to arch/ARCH/include/unistd.h
    3. Add your function to the kernel's code

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9. Loadable modules

- Allow dynamic loading and unloading of additional kernel functionality.

- Managed by: kernel/module.c

- In practice, modules are .ko files (.o prior to 2.6)

- A single module's source tree can have a very complex hierarchy.

- Every module must export functions using:

  module_init()   =>   called on insmod

  module_exit()   =>   called on rmmod

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- Module macros:

```
MODULE_AUTHOR        => module's author
MODULE_LICENSE       => module's license (taint)
MODULE_DESCRIPTION   => module's description
EXPORT_SYMBOL        => export symbol for use by other
                        modules
MODULE_PARM_DESC     => module parameter description
    ...
```

- Requesting modules from within the kernel:

*int request_module(const char * name, ...)*

10. Interrupt and exception management

- ## Relevant files:
  - ### arch/x86/kernel/
        i8259.c   =>   initialization and handling of 8259
        irq.c   =>   arch-dependent irq handling
        entry.S   =>   main assembly entry point
        traps.c   =>   CPU exception handling
  - ### kernel/irq/
        handle.c   =>   arch-independent irq handling (exc. ARM)
- ## Exception examples:
  - ### debug, overflow, bounds, fp, fault, nmi, etc.
- ## Exceptions path:
  1. arch/x86/kernel/entry.S: hard-coded assembly
  2. arch/x86/kernel/traps.c: custom function or macro generated (DO_ERROR).

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- Hardware interrupt code:
  - arch/x86/kernel/entry.S: irq_entries_start

- Hardware interrupt path:
  1. Assembly in entry.S

  2. *do_IRQ()* in arch/x86/kernel/irq.c

  3. *__do_IRQ()* in kernel/irq/handle.c:

     1. Acks IRQ using callback from arch/x86/kernel/ i8259.c:*mask_and_ack_8259A()*

     2. Calls *handle_IRQ_event()*

  4. Handler provided by device driver is invoked

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- Deferring handling with enabled interrupts:
  - Softirq:
    - Statically allocated
    - Reentrant (must use locking mechanisms to protect data)
    - Softirqs of same type can run on many CPUs in the same time.
  - Tasklets:
    - Built on top of softirqs
    - Dynamically allocatable
    - The same tasklet type can't run on 2 CPUs in the same time.
  - Bottom-halves:
    - Built on top of tasklets
    - Statically allocated
    - There can only be one BH running at one time in the entire system.

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11. Timing

- Time-keeping variables in the kernel: x86

jiffies	=>	incremented at every clock tick
wall_jiffies	=>	last time xtime was updated
TSC	=>	CPU-maintained counter (64-bit)

- Time handling:
  - arch/x86/kernel/time.c
- Finding out what time it is:
  - *do_gettimeofday()*
  - *get_cycles()*
  - *jiffies*

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12. Locking primitives

- Never do cli / sti

- Always use existing locks to do the dirty-work

- Variants:

  - Spinlocks with IRQ disabling: good for int handlers

    spin_lock_irqsave(&lock_var, cpu_flags);

    ....

    spin_unlock_irqrestore(&lock_var, cpu_flags);

  - Vanilla spinlocks: good for most code not in int

    spin_lock(&lock_var);

    ....

    spin_unlock(&lock_var);

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- Read/write locks:

  - In reader:

    read_lock_irqsave(&lock_var, cpu_flags);
        ....
    read_unlock_irqrestore(&lock_var, cpu_flags);

  - In writer:

    write_lock_irqsave(&lock_var, cpu_flags);
        ....
    write_unlock_irqrestore(&lock_var, cpu_flags);

- For a complete list, have a look at include/linux/spinlock.h.

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13. Kernel startup

Explanation for TQM860 PPC board

0. Kernel entry point:

arch/ppc/boot/common/crt0.S:*_start*

1. *_start* calls on:

arch/ppc/boot/simple/head.S:*start*

2. *start* calls on:

arch/ppc/boot/simple/relocate.S:*relocate*

3. *relocate* calls on:

arch/ppc/boot/simple/misc-embedded.c: *load_kernel()*

4. *load_kernel()* initializes the serial line and uncompresses kernel starting at address 0.

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6. *relocate* jumps to address 0x00000000, where kernel start address is.
7. arch/ppc/kernel/head_8xx.S: *__start*
8. *__start* eventually calls init/main.c:*start_kernel()*
9. *load_kernel()* returns to *relocate*
10. *start_kernel()* does:
    1. Locks kernel
    2. *setup_arch()*
    3. *sched_init()*
    4. *parse_args()*
    5. *trap_init()*
    6. *init_IRQ()*

7. *time_init()*

8. *console_init()*

9. *mem_init()*

10. *calibrate_delay()*   =>   *loops_per_jiffy*

11. *rest_init()*

11. *rest_init()* does:

1. Start `init` thread

2. Unlocks the kernel

3. Becomes the idle task

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12. The `init` task:

1. *lock_kernel()*

2. *do_basic_setup()* => call various *init()* fcts

3. *prepare_namespace()* => mount rootfs

4. *free_initmem()*

5. *unlock_kernel()*

6. *execve()* on the init program (`/sbin/init`)

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14. Dealing with kernel failure

- Kernel is mature and stable, but can fail
- Kernel failure results in call to kernel/panic.c:*panic()*
- Reboot is as according to panic= boot param or default (180s)
- Default panic message goes to console
- Need to have your own panic handler
- Main list of callbacks on panic: *panic_notifier_list*.
- Register using *notifier_chain_register()*

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```c
#include <linux/kernel.h>
#include <linux/init.h>
#include <linux/notifier.h>

static int on_screen_panic_event(struct notifier_block *,
                                 unsigned long,
                                 void *);


static struct notifier_block on_screen_panic_block = {
        notifier_call:    on_screen_panic_event,
        next:             NULL,
        priority:         INT_MAX
};


int __init register_on_screen_panic(void)
{
        printk("Registering on-screen panic notifier \n");

        notifier_chain_register(&panic_notifier_list,
                                &on_screen_panic_block);

        return 0;
}
```

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```
void write_raw_user_screen(void)
{
        ...
}

static int on_screen_panic_event(struct notifier_block *this,
                                 unsigned long event,
                                 void *ptr)
{
        write_raw_user_screen(  );

        return NOTIFY_DONE;
}

__initcall(register_on_screen_panic);
```

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Device driver overview

1. Licensing reminder
2. Device driver model
3. Writing a char device driver
4. Writing a block device driver
5. Writing a network device driver
6. Writing an MTD map file
7. Writing a framebuffer driver
8. Time-keeping
9. Memory needs

10.Hardware access

11.Interrupt handling

12.Printing out messages to console

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1. Licensing reminder

- Although the use of binary-only modules is widespread, Kernel modules are not immune to kernel GPL.
- Many kernel developers have come out rather strongly against binary-only modules.
- If you are linking a driver as built-in, then you are most certainly forbidden from distributing the resulting kernel under any license other than the GPL.
- If you're wary of the GPL, push critical driver-intelligence to user-space.

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2. Device driver model

- Device files
    - Everything is a file in Unix, including devices
    - All devices are located in the /dev directory
    - Only networking devices do not have /dev nodes
    - Every device is identified by major / minor number
    - Can be allocated statically (devices.txt)
    - Can be allocated dynamically
    - To see devices present: `$ cat /proc/devices`
    - Alternatives: devfs, sysfs (used to be driverfs)

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- Char devices:
  - Stream-oriented devices
  - Manipulated using: *struct file_operations**
- Block devices:
  - Disk-oriented devices
  - Manipulated using: *struct block_device_operations**
- Networking devices
  - All networking devices
  - Manipulated using: *struct net_device**

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- Subsystem drivers:

  - USB:

    *struct usb_driver ***

  - MTD:

    Chip driver: *struct mtd_chip_driver ***

    Device: *struct mtd_info ***

  - Framebuffer:

    *struct fb_info ***

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3. Writing a char device driver

- Register char dev during module initialization

- Char dev registration: include/linux/fs.h

```
int register_chrdev(unsigned int,
                    const char *,
                    struct file_operations *);
```

- First param: Major number
- Second param: Device name (as displayed in /proc/devices)
- Third param: File-ops
  - Defined in include/linux/fs.h

  - Contains callbacks for all possible operations on a char device.

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```c
struct file_operations {
        struct module *owner;
        loff_t (*llseek) (struct file *, loff_t, int);
        ssize_t (*read) (struct file *, char __user *, size_t, loff_t *);
        ssize_t (*aio_read) (struct kiocb *, char __user *, size_t, loff_t);
        ssize_t (*write) (struct file *, const char __user *, size_t, loff_t *);
        ssize_t (*aio_write) (struct kiocb *, const char __user *, size_t, loff_t);
        int (*readdir) (struct file *, void *, filldir_t);
        unsigned int (*poll) (struct file *, struct poll_table_struct *);
        int (*ioctl) (struct inode *, struct file *, unsigned int, unsigned long);
        long (*unlocked_ioctl) (struct file *, unsigned int, unsigned long);
        long (*compat_ioctl) (struct file *, unsigned int, unsigned long);
        int (*mmap) (struct file *, struct vm_area_struct *);
        int (*open) (struct inode *, struct file *);
        int (*flush) (struct file *);
        int (*release) (struct inode *, struct file *);
        int (*fsync) (struct file *, struct dentry *, int datasync);
        int (*aio_fsync) (struct kiocb *, int datasync);
        int (*fasync) (int, struct file *, int);
        int (*lock) (struct file *, int, struct file_lock *);
        ssize_t (*readv) (struct file *, const struct iovec *, unsigned long, loff_t *);
        ssize_t (*writev) (struct file *, const struct iovec *, unsigned long, loff_t *);
        ssize_t (*sendfile) (struct file *, loff_t *, size_t, read_actor_t, void *);
        ssize_t (*sendpage) (struct file *, struct page *, int, size_t, loff_t *, int);
        unsigned long (*get_unmapped_area)(struct file *, unsigned long, unsigned ...
        int (*check_flags)(int);
        int (*dir_notify)(struct file *filp, unsigned long arg);
        int (*flock) (struct file *, int, struct file_lock *);
};
```

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- Call *register_chrdev()* and pass it a valid *file_operations* structure.

- Return 0 from initialization function to tell insmod that everything is OK.

- That's it. Every time the device in /dev having the same major number as the one you registered is opened, you driver will be called.

- To remove char dev on rmmod:

```
int unregister_chrdev(unsigned int,
                      const char *);
```

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4. Writing a block device driver

- Register block dev during module initialization
- Block dev registration: include/linux/fs.h

```
int register_blkdev(unsigned int,
                         const char *);
```

- First param: Major number
- Second param: Device name
- Disk allocation: include/linux/genhd.h

```
struct gendisk *alloc_disk(int minors);
```

- Block queue registration: include/linux/blkdev.h

```
extern void blk_init_queue(request_fn_proc *,
                   spinlock_t *);
```

- Queue of pending I/O operations for device

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- First param: Queue handler function

- Second param: Lock for accessing queue

- Call *register_blkdev().*

- Call *alloc_disk()* and pass it the number of disks.

- Call *blk_init_queue()* and pass it a valid callback.

- Return 0 from init function to tell insmod status

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- Now, all block operations on your device (/dev entry with same major number as driver) will be queued to your driver.

- To remove block dev on rmmod:

```
void blk_cleanup_queue(request_queue_t *);
void put_disk(struct gendisk *disk);
int unregister_blkdev(unsigned int, const char *);
```

5. Writing a network device driver

- Register net dev during module initialization
- Net dev registration: include/linux/netdevice.h

```
int        register_netdevice(struct net_device *dev);
```

- Param: net device ops
  - Defined in include/linux/netdevice.h
  - Contains all callbacks related to network devices
  - This is a huge structure with A LOT of fields
- Call *register_netdevice()* and pass it a valid *net_device* structure.
- Return 0 as status to insmod

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- Your device will need to be *opened* by the kernel in response to an *ifconfig* command.

- Your *open()* function must allocate a packet queue to deal with packets sent to your device.

- Calling your device will depend on packet routing at the upper layers of the stack.

- To remove: `unregister_netdev(struct net_device *dev);`

6. Writing an MTD map file

- Must find device in memory and then register it

- Finding a device in memory: include/linux/mtd/map.h

```
struct mtd_info *do_map_probe(char *name,
                                struct map_info *map);
```

- First param: Type of probe (ex: "cfi_probe")

- Second param: map-info

  - Defined in include/linux/mtd/map.h

  - Information regarding size and buswidth

  - Functions for accessing chip

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```
struct map_info {
char *name;
unsigned long size;
unsigned long phys;
#define NO_XIP (-1UL)

void __iomem *virt;
void *cached;

int bankwidth;
#ifdef CONFIG_MTD_COMPLEX_MAPPINGS
map_word (*read)(struct map_info *, unsigned long);
void (*copy_from)(struct map_info *, void *, unsigned long, ssize_t);

void (*write)(struct map_info *, const map_word, unsigned long);
void (*copy_to)(struct map_info *, unsigned long, const void *, ssize_t);
#endif
void (*inval_cache)(struct map_info *, unsigned long, ssize_t);

/* set_vpp() must handle being reentered -- enable, enable, disable
   must leave it enabled. */
void (*set_vpp)(struct map_info *, int);

unsigned long map_priv_1;
unsigned long map_priv_2;
void *fldrv_priv;
struct mtd_chip_driver *fldrv;
};
```

- Once located, use *add_mtd_partitions()* to provide partition information to MTD subsystem.

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- *add_mtd_partition()* is in include/linux/mtd/partitions.h

```
int add_mtd_partitions(struct mtd_info *,
                       struct mtd_partition *,
                       int);
```

- First param: pointer returned by *do_map_probe()*

- Second param: partition information as we saw earlier.

- Third param: number of partitions

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7. Writing a framebuffer driver

- Register framebuffer during module init
- Framebuffer registration: include/linux/fb.h

```
int register_framebuffer(struct fb_info *fb_info);
```

- Param: fb-info

  - Defined in include/linux/fb.h
  - Contains callbacks for all framebuffer operations

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```
struct fb_info {
        int node;
        int flags;
        struct fb_var_screeninfo var; /* Current var */
        struct fb_fix_screeninfo fix; /* Current fix */
        struct fb_monspecs monspecs;  /* Current Monitor specs */
        struct work_struct queue;      /* Framebuffer event queue */
        struct fb_pixmap pixmap; /* Image hardware mapper */
        struct fb_pixmap sprite; /* Cursor hardware mapper */
        struct fb_cmap cmap;            /* Current cmap */
        struct list_head modelist;      /* mode list */
        struct fb_ops *fbops;
        struct device *device;
#ifdef CONFIG_FB_TILEBLITTING
        struct fb_tile_ops *tileops;    /* Tile Blitting */
#endif
        char __iomem *screen_base;    /* Virtual address */
        unsigned long screen_size;    /* Amount of ioremapped VRAM or 0 */
        void *pseudo_palette;         /* Fake palette of 16 colors */
#define FBINFO_STATE_RUNNING0
#define FBINFO_STATE_SUSPENDED   1
        u32 state;                    /* Hardware state i.e suspend */
        void *fbcon_par;                /* fbcon use-only private area */
        /* From here on everything is device dependent */
        void *par;
};
```

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- Call *register_framebuffer()* and pass it a valid *fb_info* structure.

- Return 0 from init code

- Access the /dev/fbX (where X is your framebuffer's registration order in relationship to other fb drivers) results in the functions provided in *fb_info* to be called.

- To remove fb dev on rmmod:

```
int unregister_framebuffer(struct fb_info *fb_info);
```

8. Time-keeping

- **Simple ways to get the time**
  - *jiffies*: updated at every kernel tick
  - *do_gettimeofday()*: good precision depending on arch
  - *get_cycles()*: arch-independent call to get CPU cycle count.
- **Being notified in due time:**
  - Use timers: include/linux/timer.h
    - *jiffies* resolution
    - Use *struct timer_list*: contains expiry and callback
    - Initialize timer: *init_timer()*
    - Add timer to global timer list: *add_timer()*
    - Remove timer before expiry: *del_timer()*

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9. Memory needs

- Main kernel memory functions:

    - *kmalloc(size, type)*: up to 128KB of memory

    - *vmalloc(size)*: get large contiguous virtual memory

- Main types of memory allocation:

    - GFP_KERNEL   =>   normal alloc / may sleep

    - GFP_ATOMIC   =>   int handlers / never sleeps

    - GFP_USER   =>   user-space / low priority

    - … See include/linux/slab.h for full list

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10. Hardware access

- Main functions to be able to access hardware:
  - ISA:
    - Typical inb/outb
  - PCI:
    - Checking use of mem region: *check_mem_region()*
    - Requesting region: *request_mem_region()*
    - Releasing region: *release_mem_region()*
    - Map physical region to VM: *ioremap()*

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11. Interrupt handling

- Setting up an interrupt handler:
```
extern int request_irq(unsigned int,
        irq_handler_t, unsigned long, const char *, void *);
```
- First param: IRQ number
- Second param: handler
- Third param: flags for OS int delivery
- Four param: device name
- Fifth param: provide device ID in case of shared interrupts.
- Disabling interrupt handler:
```
void free_irq(unsigned int, void *);
```

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12. Printing out messages to console

- Meet the kernel's printf: *printk()*

- Defined: include/linux/kernel.h

  ```
  int printk(const char * fmt, ...)
  ```

- Implemented: kernel/printk.c

- Can loose data in cases of large output

- Widely-used throughout kernel sources

- Don't call while holding lock, has lock contention of its own.

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A Quick Java Introduction

1. Parts

2. Hello World

3. What's missing from C/C++?

4. What's different?

1. Parts

- JDK
  - Compiler
  - Libraries
- JRE
  - JVM
- Eclipse

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2. Hello World

- The code:

```
class HelloWorld {
    public static void main(String[] args) {
        System.out.println("Hello World!");
    }
}
```

- Compiling:

```
$ javac HelloWorld.java
```

- Running:

```
$ java HelloWorld
Hello World!
$
```

3. What's missing from C/C++?

- Preprocessor:
  - #include
  - #define
  - #ifdef/#endif
- Definitions:
  - typedef
  - struct
  - union
  - enum

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- Keywords:
  - goto
- Pointers:
  - malloc/free
- Strings as arrays of char:
  - Use `"foo".toCharArray()` to get a char array
  - Use `foo = new String(charArray)` to get a String

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4. What's different?

- Garbage collection:

```
String myStr = new String("foo");
myStr = null;
myStr = new String("bar");
```

- String concatenation:

```
strC = strA + strB;
```

- Reflection:

```
// Direct call
new MyClass().foo();

// Call through reflection reflection
Class cls = Class.forName("MyClass");
cls.getMethod("foo", null).invoke(cls.newInstance(), null);
```

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- Interfaces:

```
interface Foo
{
    bar();
}

public class MyClass implements Foo {
    public bar() {
        ...
    }
}
```

- Can implement multiple interfaces (v. multiple inheritance)

- All methods declared as part of a class – no standalone "functions"

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- Anonymous classes:

```
public class MyClass {
        public static void main(String args[]) {
                new Thread(new Runnable() {
                        @Override
                        public void run() {
                                System.out.println("Hello Anon");
                        }
                }).start();
        } // end main
}
```

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- Inheritance:

```
public class Foo extends Bar {
    ...
}
```

- Package (first line in source file):

```
package com.foo.mypackage;
```

- Importing (using a package):

```
import com.foo.mypackage;
```

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- # Threads:

```
public class MyThread extends Thread {
    public void run() {
        System.out.println("Hello Thread World!");
    }

    public static void main(String args[]) {
        (new MyThread()).start();
    }
}
```

- # Synchronization:

```
public synchronized void foo() {
    ...
}
```

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- Checking type:

```
public class Foo extends Bar {
    ...
}
...
    foo myFoo = new Foo()
    if (myFoo instanceof Bar) {
        ...
    }
```

- Overrides:

```
public class Bar {
    public void aMethod() {
    ...
    }
}

public class Foo extends Bar {
    @Override
    public void aMethod() {
    ...
    }
```

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- Arrays:

```
int[] myArray = new int[100];
```

- JavaDoc
- Junit
- JNI

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- Packages:

```
java.applet
java.awt
java.awt.color
java.awt.datatransfer
java.awt.dnd
java.awt.event
java.awt.font
java.awt.geom
java.awt.im
java.awt.im.spi
java.awt.image
java.awt.image.renderable
java.awt.print
java.beans
java.beans.beancontext
java.io
java.lang
java.lang.ref
java.lang.reflect
java.math
java.net
java.nio
java.nio.channels
java.nio.channels.spi
java.nio.charset
java.nio.charset.spi
```

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```
java.rmi
java.rmi.activation
java.rmi.dgc
java.rmi.registry
java.rmi.server
java.security
java.security.acl
java.security.cert
java.security.interfaces
java.security.spec
java.sql
java.text
java.util
java.util.jar
java.util.logging
java.util.prefs
java.util.regex
java.util.zip
javax.accessibility
javax.crypto
javax.crypto.interfaces
javax.crypto.spec
javax.imageio
javax.imageio.event
javax.imageio.metadata
javax.imageio.plugins.jpeg
javax.imageio.spi
javax.imageio.stream
javax.naming
javax.naming.directory
javax.naming.event
javax.naming.ldap
javax.naming.spi
```

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```
javax.net
javax.net.ssl
javax.print
javax.print.attribute
javax.print.attribute.standard
javax.print.event
javax.rmi
javax.rmi.CORBA
javax.security.auth
javax.security.auth.callback
javax.security.auth.kerberos
javax.security.auth.login
javax.security.auth.spi
javax.security.auth.x500
javax.security.cert
javax.sound.midi
javax.sound.midi.spi
javax.sound.sampled
javax.sound.sampled.spi
javax.sql
javax.swing
javax.swing.border
javax.swing.colorchooser
javax.swing.event
javax.swing.filechooser
javax.swing.plaf
javax.swing.plaf.basic
javax.swing.plaf.metal
javax.swing.plaf.multi
javax.swing.table
javax.swing.text
javax.swing.text.html
javax.swing.text.html.parser
javax.swing.text.rtf
javax.swing.tree
javax.swing.undo
```

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```
javax.transaction
javax.transaction.xa
javax.xml.parsers
javax.xml.transform
javax.xml.transform.dom
javax.xml.transform.sax
javax.xml.transform.stream
org.ietf.jgss
org.omg.CORBA
org.omg.CORBA.DynAnyPackage
org.omg.CORBA.ORBPackage
org.omg.CORBA.TypeCodePackage
org.omg.CORBA.portable
org.omg.CORBA_2_3
org.omg.CORBA_2_3.portable
org.omg.CosNaming
org.omg.CosNaming.NamingContextExtPackage
org.omg.CosNaming.NamingContextPackage
org.omg.Dynamic
org.omg.DynamicAny
org.omg.DynamicAny.DynAnyFactoryPackage
org.omg.DynamicAny.DynAnyPackage
org.omg.IOP
org.omg.IOP.CodecFactoryPackage
org.omg.IOP.CodecPackage
org.omg.Messaging
```

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```
org.omg.PortableInterceptor
org.omg.PortableInterceptor.ORBInitInfoPackage
org.omg.PortableServer
org.omg.PortableServer.CurrentPackage
org.omg.PortableServer.POAManagerPackage
org.omg.PortableServer.POAPackage
org.omg.PortableServer.ServantLocatorPackage
org.omg.PortableServer.portable
org.omg.SendingContext
org.omg.stub.java.rmi
org.w3c.dom
org.xml.sax
org.xml.sax.ext
org.xml.sax.helpers
```

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Thank you ...

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